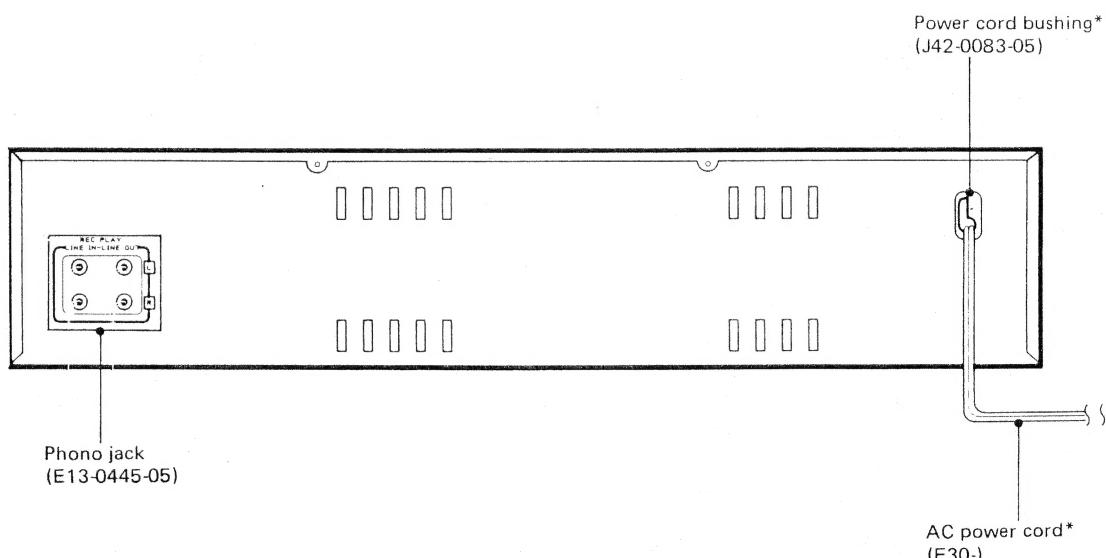
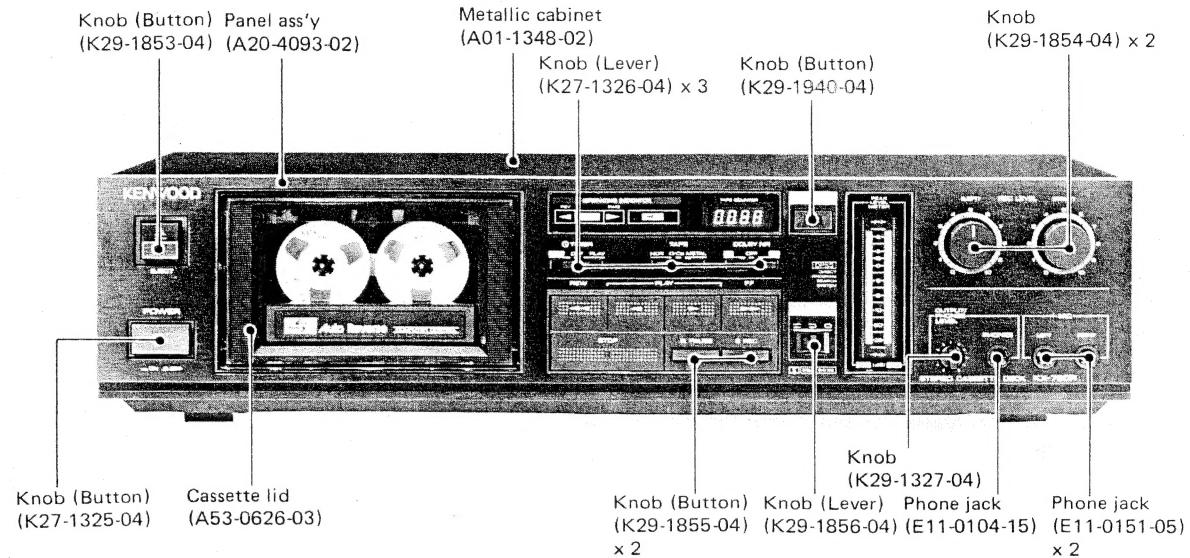


KENWOOD SERVICE MANUAL

KENWOOD

KX-790R

STEREO CASSETTE DECK

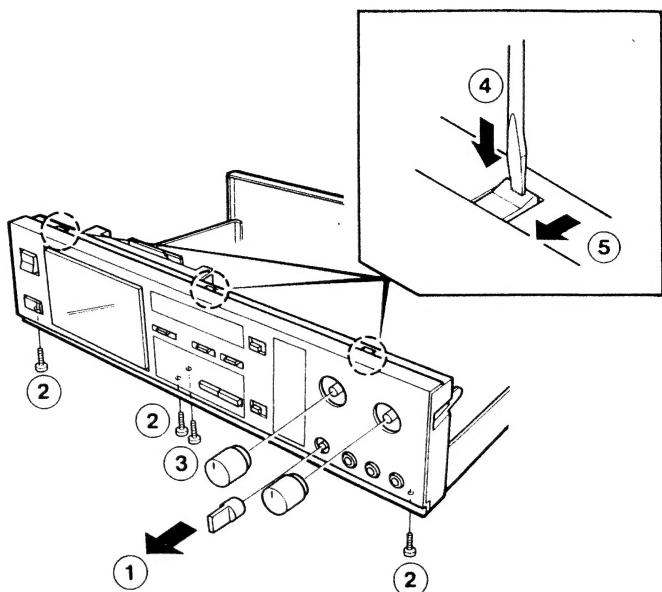


* Refer to parts list on page 40.

DISASSEMBLY FOR REPAIR

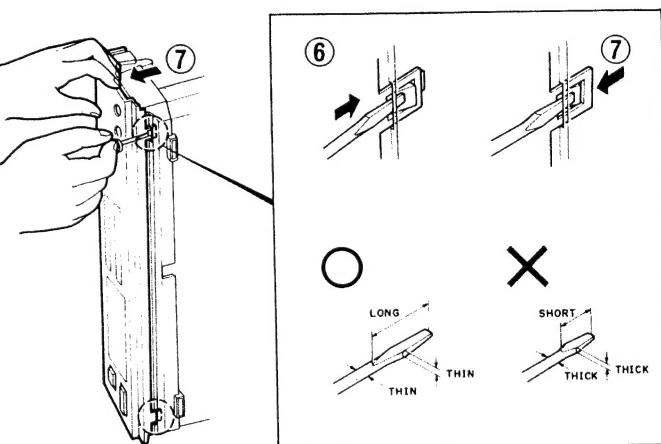
FOR REPAIR OF PCBs ATTACHED TO SUB PANEL

1. Pull out the knobs forward (①).
2. Remove 3 screws at the bottom side of the front panel and 1 screw retaining the mounting hardware (②, ③).
3. Push the snap down to release the top side of the front panel (④, ⑤).



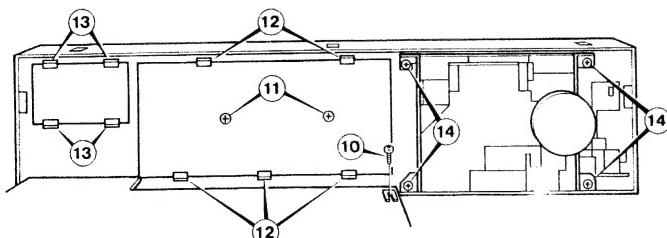
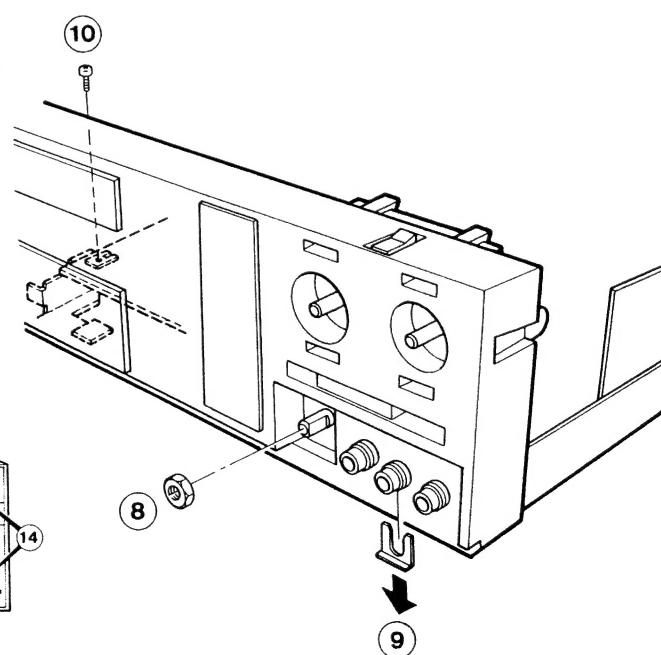
4. By using a flat blade screw driver, push the snap up to release the bottom side of the front panel from the slit and pull the front panel forward (⑥, ⑦).

Note : Use a screw driver that satisfies the qualifications shown in the figure to avoid damage to the sub panel slit.



5. Slide out the jack mounting hardware and remove the hexagon nut from the VR axis (⑧, ⑨), also remove the screw retaining the pcb to the mounting hardware (⑩).

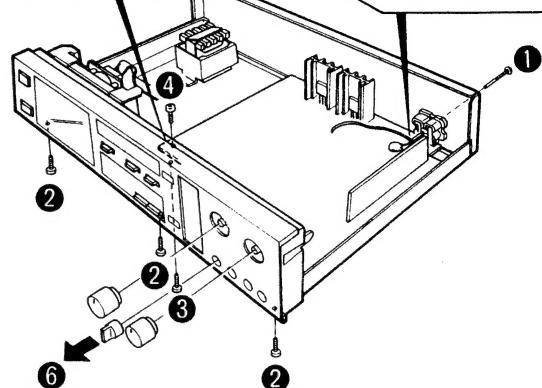
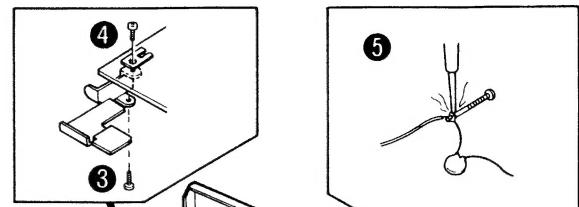
6. Remove 2 screws retaining the SW & DISPLAY pcb and release the pcb from the claws for replacement of components on the pcb (⑪, ⑫).
7. Release from the claws on the VR pcb for replacement of VRs (⑬).
8. Remove 4 screws from the mechanism assembly for repair of mechanism (⑭).



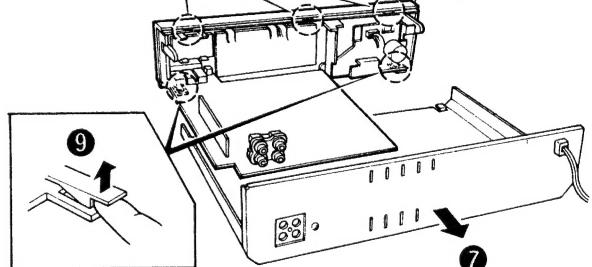
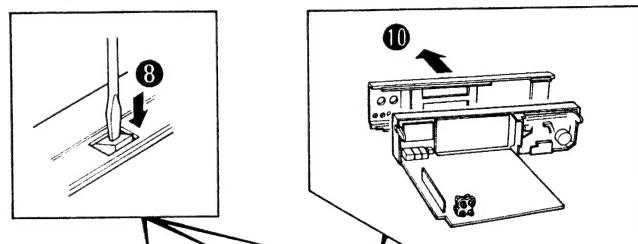
DISASSEMBLY FOR REPAIR

FOR REPAIR OF X26-1090-10 AND OTHERS

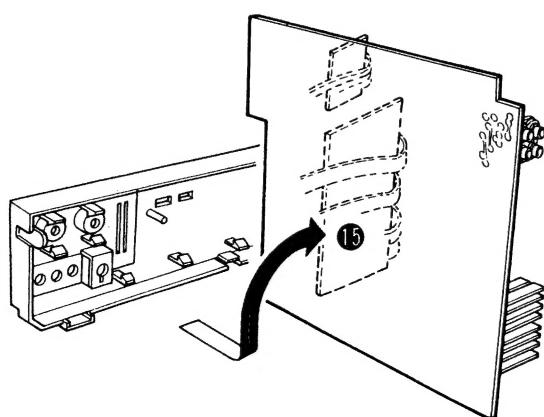
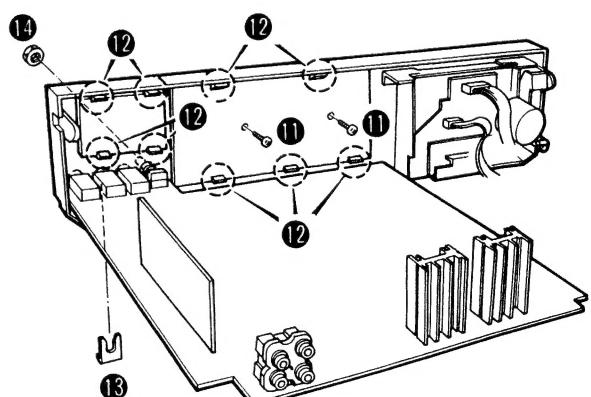
1. Unsolder the GND lead and the capacitor from the GND screw at the phono jack and remove the screw (①, ②).
2. Pull out the knobs frontward (③).
3. Remove 3 screws at the bottom side of the front panel (④). Remove screws retaining the mounting hardware from the bottom and from the pcb (⑤, ⑥).



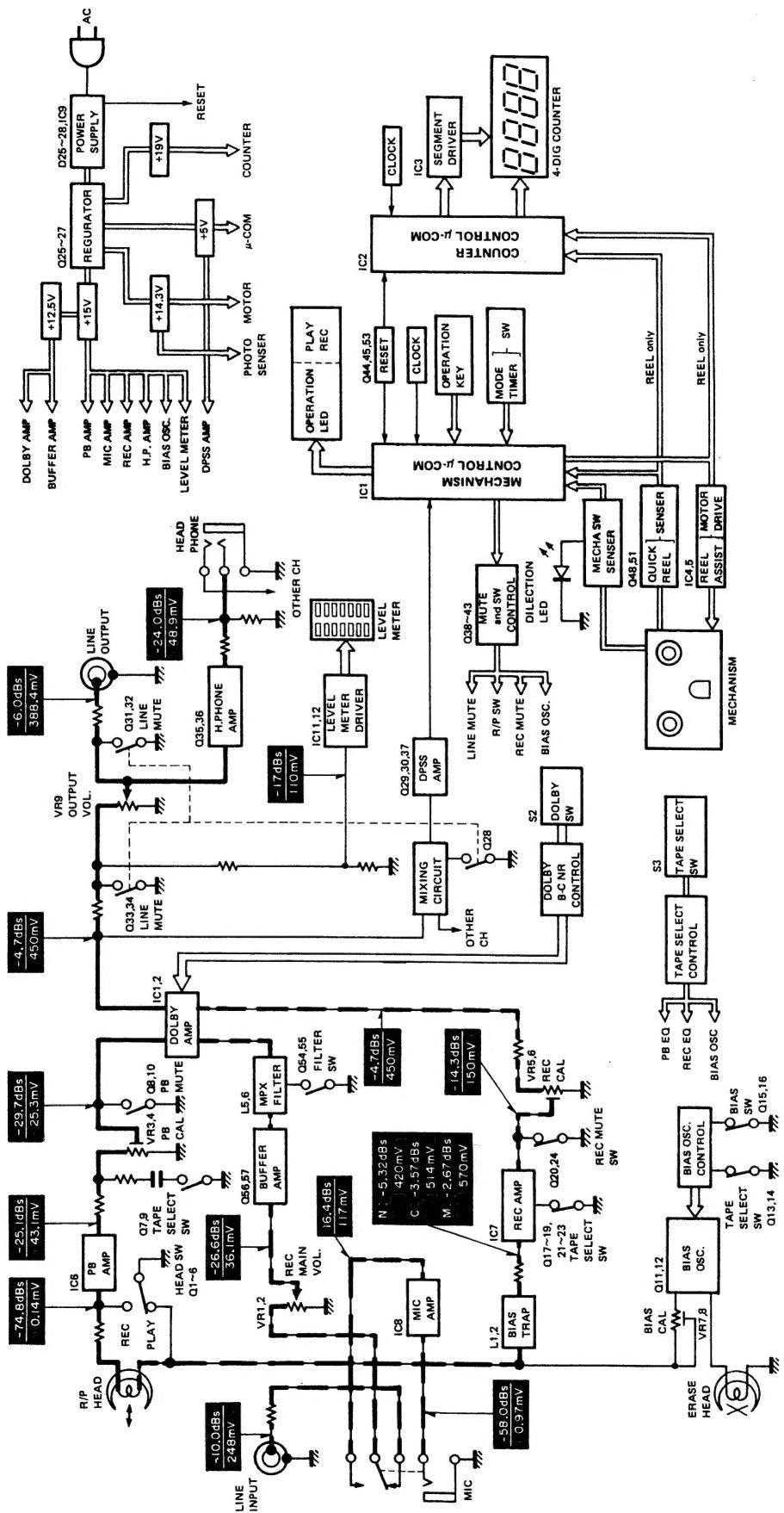
4. Slide the chassis out from the sub panel with the rear panel attached to it (⑦).
5. Push the snap down to release the top side of the front panel and by lifting the snap from the bottom release the bottom side of the front panel (⑧, ⑨).
6. Remove the front panel (⑩).



7. Remove 2 screws retaining the SW & DISPLAY pcb and release the pcbs from the claws (⑪, ⑫).
8. Slide out the jack mounting hardware and remove the hexagon nut from the VR axis (⑬, ⑭).
9. Turn the pcb (X26-1090-10) as shown in the figure for replacement of components on these pcbs (⑮).



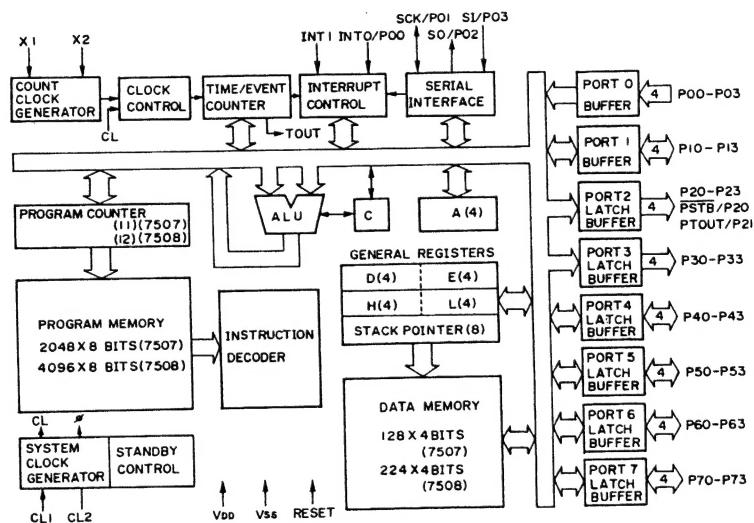
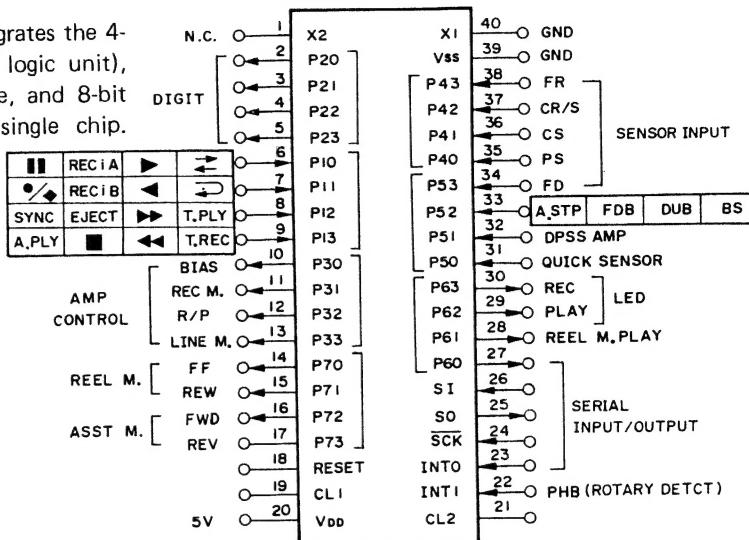
BLOCK LEVEL DIAGRAM



CIRCUIT DESCRIPTION

IC1 μ PD7507C One-chip 4-bit microcomputer

μ PD7507 is a 4-bit microcomputer which integrates the 4-bit parallel processing ALU (arithmetic and logic unit), ROM, RAM, I/O ports, 8-bit serial interface, and 8-bit programmable timer/event counter into a single chip.



Description of port functions of the microcomputer (slave μ PD7507C-099) for the KX-790R

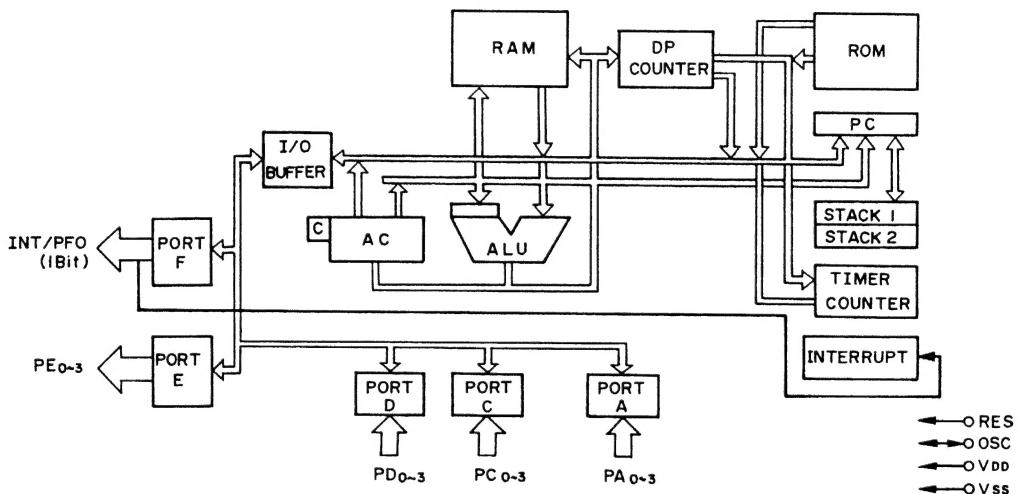
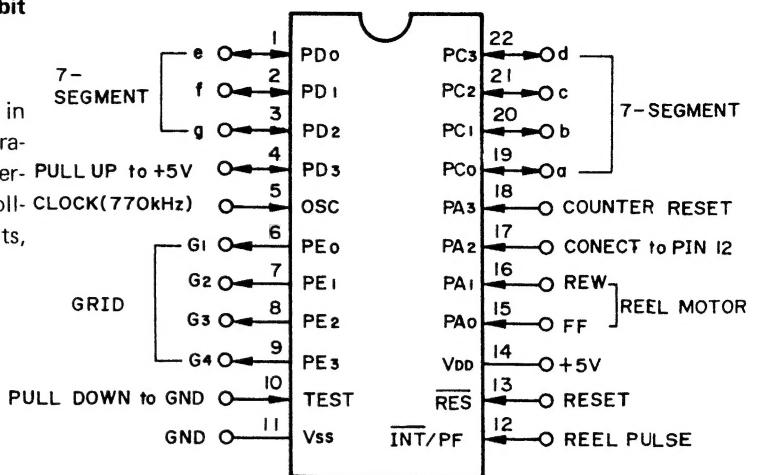
Pin No.	Name	I/O	Functions
2~5	P20~P23	O	DIGIT Digit signal outputs.
6~9,33	P10~P13,PS2	I	Key inputs.
10~13	P30~P33	O	AMP Bias, REC MUTE, REC/PLAY, LINE MUTE outputs.
14,15,28	P70,P71,P61	O	REEL M. Outputs for controlling the reel motor.
16,17	P72,P73	O	AST.M. Outputs for controlling the assist motor.
22	PHA	I	PHB Input for detecting the speed of deck mechanism B.
23	INT0	I	Intercommunication request input.
24	SCK	I	Serial shift clock input.
25	SO	O	Serial data output.
26	SI	I	Serial data input.
27	P60	O	Shift clock request output.
29,30	P62,P63	O	PLAY,REC Outputs for the PLAY LED and REC LED.
31	P50	I	QUICK Quick reverse signal input.
32	P51	I	DPSS Input for detecting the non-recorded portion.
34~38	P53,P40~P43	I	Inputs for the mechanism position sensor.

CIRCUIT DESCRIPTION

IC2 LM6417E N-channel E/D MOS LSI One-chip 4-bit microcomputer for controlling

1. Outline

LM6417E is an N-channel MOS 4-bit microcomputer in which ROM, RAM, ALU, I/O ports, timer, clock generator have been integrated into a single chip. The internal memory capacity of this microcomputer for controlling is ROM 1024 bytes (or 1 kbyte), RAM 64 x 4 bits, and the I/O ports have 17 pins.

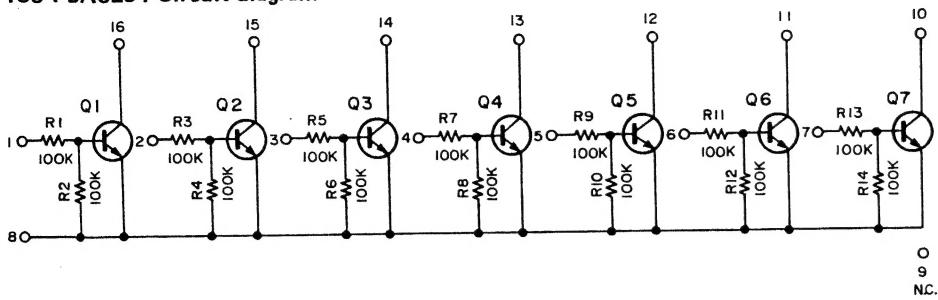


Description of port functions of LM6417E-444 for the KX-790R

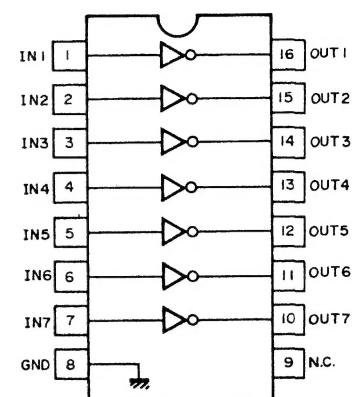
Pin No.	Name	I/O	Functions	
1	PDO	O	e	
2	PD1	O	f	7-segment driver for the FIP 4-digit counter.
3	PD2	O	g	
6	PE0	O	G1	
7	PE1	O	G2	Grid driver for the FIP 4-digit counter.
8	PE2	O	G3	
9	PE3	O	G4	
12	INT/PFO	I	Reel disk speed detection pulse input.	
15	PA0	I	REW	Mechanism travel direction detect input (detects the output for controlling
16	PA1	I	FF	the reel motor from IC1 μ PD7507C-099.)
18	PA3	I	Counter reset key input.	
19	PC0	O	a	
20	PC1	O	b	7-segment driver for the FIP 4-digit counter.
21	PC2	O	c	
22	PC3	O	d	

CIRCUIT DESCRIPTION

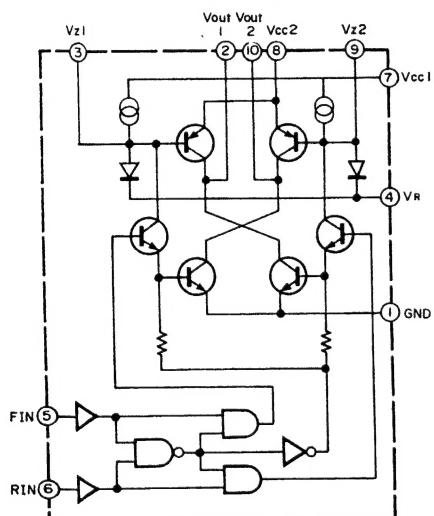
IC3 : BA6251 Circuit diagram



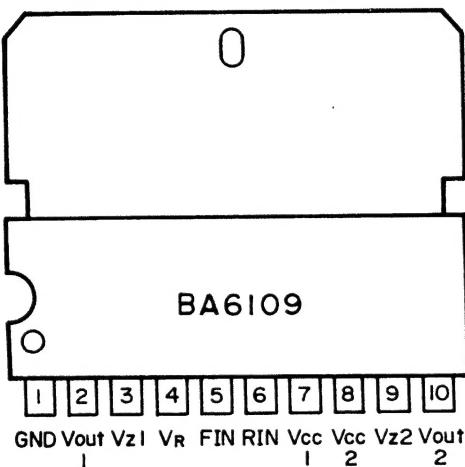
IC3 : BA6251 Pin configuration (Top view)



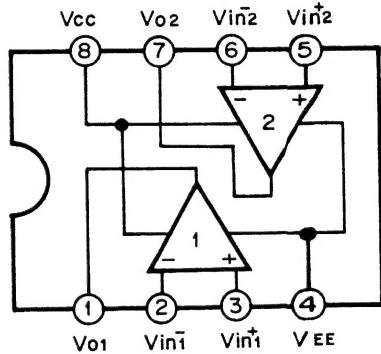
IC4,5 : BA6109 Block diagram



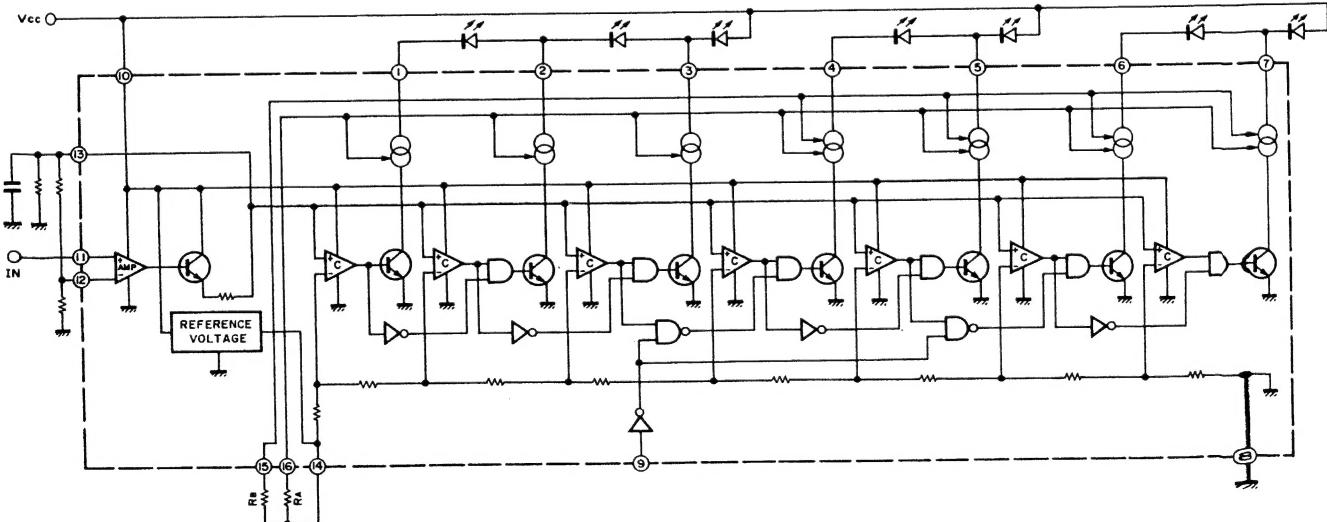
IC4,5 : BA6109 Pin configuration (Top view)



IC7,8 : AN6556 Pin configuration (Top view)



IC11,12 : AN6882 Block diagram



CIRCUIT DESCRIPTION

List of element actions

Name of the PCB: R/P PCB (X26-1090-10)

Elements	Applications/functions	Operation/conditions/compatibility																
Q1,Q2,Q4,Q5	Head select switches	These switches are controlled by switch controllers consisting of Q38 to Q43 which receive the output from pin 12 (R/P) of mechanism control microcomputer IC1. During rec & rec pause modes: OFF During any other mode: ON																
Q3,Q6	Head select switches	Operate in complement with Q1, Q2, Q4 and Q5. Since these switches are inverted by Q40, they turn ON during rec and rec pause modes and OFF in any other mode.																
Q7,Q9	Playback equalizer select switches	These switches are controlled by tape selector switch S3. When normal tape (120 μ s) is used: OFF When metal/chrome tape (70 μ s) is used: ON																
Q8,Q10	Playback mute switches	Like head select switches Q3 and Q6, these switches are controlled by the inverted signal from Q40, and mute the output from the playback equalizer amp, so that bias does not leak to the playback input terminal of the Dolby unit. During rec & rec pause modes: ON																
Q11	Bias oscillator power supply	The signal from pin 10 (BIAS) of IC1 controls bias ON/OFF switches Q15 and Q16, which in turn control Q11. During REC mode: Pin 10 of IC1 goes low with the result that Q16 turns off and Q15 turns on.																
Q12	Bias oscillator coil driver	This transistor drives the primary winding of bias oscillator transformer L7.																
Q13,Q14	Bias oscillator level select switches	These switches are controlled by tape selector switch S3, function as shown in the table below.																
		<table border="1"> <thead> <tr> <th></th><th>Normal</th><th>Chrome</th><th>Metal</th></tr> </thead> <tbody> <tr> <td>Q13</td><td>ON</td><td>OFF</td><td>OFF</td></tr> <tr> <td>Q14</td><td>OFF</td><td>ON</td><td>OFF</td></tr> </tbody> </table>		Normal	Chrome	Metal	Q13	ON	OFF	OFF	Q14	OFF	ON	OFF				
	Normal	Chrome	Metal															
Q13	ON	OFF	OFF															
Q14	OFF	ON	OFF															
Q15,Q16	Bias ON/OFF switches	These switches are controlled by the signal from pin 10 (BIAS) of IC1.																
		<table border="1"> <thead> <tr> <th></th><th>REC</th><th>Other modes (including rec pause mode)</th></tr> </thead> <tbody> <tr> <td>Q15</td><td>ON</td><td>OFF</td></tr> <tr> <td>Q16</td><td>OFF</td><td>ON</td></tr> </tbody> </table>		REC	Other modes (including rec pause mode)	Q15	ON	OFF	Q16	OFF	ON							
	REC	Other modes (including rec pause mode)																
Q15	ON	OFF																
Q16	OFF	ON																
Q17~Q19, Q21~Q23	Recording equalizer select switches	These switches are controlled by tape selector switch S3.																
		<table border="1"> <thead> <tr> <th></th><th>Normal</th><th>Chrome</th><th>Metal</th></tr> </thead> <tbody> <tr> <td>Q17,Q21</td><td>ON</td><td>ON</td><td>OFF</td></tr> <tr> <td>Q18,Q22</td><td>OFF</td><td>ON</td><td>OFF</td></tr> <tr> <td>Q19,Q23</td><td>OFF</td><td>OFF</td><td>ON</td></tr> </tbody> </table>		Normal	Chrome	Metal	Q17,Q21	ON	ON	OFF	Q18,Q22	OFF	ON	OFF	Q19,Q23	OFF	OFF	ON
	Normal	Chrome	Metal															
Q17,Q21	ON	ON	OFF															
Q18,Q22	OFF	ON	OFF															
Q19,Q23	OFF	OFF	ON															
Q20,Q24	REC MUTE switches	These switches are controlled by the signal from pin 11 (REC MUTE) of IC1. During rec mode only: OFF During any other mode: ON (including rec pause mode)																
Q25	+ 19V constant-voltage regulated power supply	Power supply for the 4-digit, 7-segment counter.																
Q26	+ 5.6V constant-voltage regulated power supply	Power supply for ICs 1 and 2 (microcomputer) and DPSS amps (Q29, Q30 and Q37)																
Q27	+ 14.3V constant-voltage regulated power supply	Power supply for driving the motor and the photo-sensor.																
Q28	DPSS input sensitivity select switch	During play, rec, rec pause modes: OFF During any other mode: ON (including play pause mode) Pin 13 (LINE MUTE) of IC1 outputs a high level signal during the play, rec and rec pause modes as mentioned above, which switches off Q41. As a result, Q28 turns off with the consequence that the bypass filter connected to Q28 becomes conductive and is introduced to the input of DPSS amp Q29, Q30 and Q37, thereby increasing the input sensitivity. Conversely, in other modes, such as DPSS operation modes (cue, review, etc.), a low level signal is output from pin 13 (LINE MUTE) of IC1, and turns both Q41 and Q28 on, lowering the input sensitivity.																

CIRCUIT DESCRIPTION

Elements	Applications/functions	Operation/conditions/compatibility																				
Q29,Q30	DPSS amplifier	NPN 2-stage direct-coupled configuration. These amplifiers are coupled with DPSS output switch Q37 in the subsequent stage.																				
Q31,Q32 Q33,Q34	LINE OUT and headphone mute switches and meter mute switches	These switches operate in the same conditions as DPSS input sensitivity select switch Q28 and are controlled by the output from pin 13 (LINE MUTE) of IC1. During play, rec, and rec pause modes: OFF During other modes: ON (including play pause mode)																				
Q35,Q36	Headphone amplifiers	These amplifiers output in the emitter-follower configuration.																				
Q37	DPSS output switch	This switch is turned on or off by the detection output from 2-stage direct-coupled amplifiers Q29 and Q30 during the DPSS operation such as cue, review modes, etc. and the signal detecting the non-recorded portion is input to pin 32 (DPSS) of IC1 from the collector of Q37. When the non-recorded portion is detected: low When the already recorded portion is detected: high																				
Q38,Q39, Q40,Q43	REC/PLAY select switch controllers	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th></th> <th>REC + REC PAUSE</th> <th>Other modes</th> </tr> <tr> <td>Q43</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Q40</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Q39</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Q38</td> <td>OFF</td> <td>ON</td> </tr> </table> <p>The above operation is controlled by the output from pin 12 (R/P) of IC1, and a high level signal is output from pin 12 during rec & rec pause modes, and a low level signal is output from the same pin during other modes.</p>				REC + REC PAUSE	Other modes	Q43	ON	OFF	Q40	ON	OFF	Q39	ON	OFF	Q38	OFF	ON			
	REC + REC PAUSE	Other modes																				
Q43	ON	OFF																				
Q40	ON	OFF																				
Q39	ON	OFF																				
Q38	OFF	ON																				
Q41	LINE OUT mute switch controller	This transistor is controlled by the output from pin 13 (LINE MUTE) of IC1, which is active low. This is off during play, rec, and rec pause modes, and on in other modes (including play pause mode), and on when the power is switched on or off.																				
Q42	REC MUTE switch controller	This transistor is controlled by the output from pin 11 (REC MUTE) of IC1, which is active low. This is off in rec mode, on in other modes and when power is switched on or off.																				
Q44,Q45,Q53	Reset	Refer to "Microcomputer reset circuit" on the separate sheet.																				
Q46,Q47	Controllers to regulate the voltages to be applied for driving the reel motor	These transistors operate under the following conditions on receipt of the output from pin 28 (reel motor play) of IC1. <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th></th> <th>During play and rec modes</th> <th>During other modes (including pause mode)</th> </tr> <tr> <td>Output from pin 28 of IC1</td> <td>High</td> <td>Low</td> </tr> <tr> <td>Q47</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Emitter voltage of Q46</td> <td>about 3.6V</td> <td>about 6.4V</td> </tr> </table>				During play and rec modes	During other modes (including pause mode)	Output from pin 28 of IC1	High	Low	Q47	ON	OFF	Emitter voltage of Q46	about 3.6V	about 6.4V						
	During play and rec modes	During other modes (including pause mode)																				
Output from pin 28 of IC1	High	Low																				
Q47	ON	OFF																				
Emitter voltage of Q46	about 3.6V	about 6.4V																				
Q48	Quick sensor amp	This amp turns on or off by the signal from the photo-coupler for the quick sensor. This amp momentarily turns on when the tape shifts from the magnetic coating portion to the leader tape portion at the end of tape. The low level signal is input to pin 31 (QUICK) of IC1 at this time.																				
Q49,Q50	Direction LED driver	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th></th> <th>During forward mode</th> <th>During reverse mode</th> </tr> <tr> <td>Position sensor terminal</td> <td>High</td> <td>Low</td> </tr> <tr> <td>Q49</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Q50</td> <td>OFF</td> <td>ON</td> </tr> <tr> <td>D48 (LED)</td> <td>Comes on</td> <td>Goes out</td> </tr> <tr> <td>D50 (LED)</td> <td>Goes out</td> <td>Comes on</td> </tr> </table>				During forward mode	During reverse mode	Position sensor terminal	High	Low	Q49	ON	OFF	Q50	OFF	ON	D48 (LED)	Comes on	Goes out	D50 (LED)	Goes out	Comes on
	During forward mode	During reverse mode																				
Position sensor terminal	High	Low																				
Q49	ON	OFF																				
Q50	OFF	ON																				
D48 (LED)	Comes on	Goes out																				
D50 (LED)	Goes out	Comes on																				

CIRCUIT DESCRIPTION

Elements	Applications/functions	Operation/conditions/compatibility
Q51	Revolution detection amp	On receipt of the switching signal (5 pulses/revolution) proportional to the speed of the reel puck (the take-up reel in forward mode), this amp generates pulses.
Q52	PLAY LED driver	This transistor turns on or off by the output from pin 29 (PLAY LED) of IC1. During play mode, Q52 turns on, lighting LED D49.
Q54,Q55	MPX filter select switch	This is controlled by Dolby switch S2. It is off when the Dolby switch is off and on when the switch is on.
Q56,Q57	Buffer amp	Emitter-follower output.
Q58	+ 12.5V constant-voltage regulated power supply	Power supply for the Dolby amp and buffer amp.
IC1	Mechanism controller	Controls the mechanism operation. Refer to the operation and function description of IC1 (μ PD7507C-099).
IC2	Counter controller	This IC has functions to drive the FIP 4-digit 7-segment counter, detect the reel puck revolution and detect the mechanism travel direction. Refer to the operation and function description of IC2 (LM6417E-444).
IC3	Transistor array for driving the 7-segment counter	Incorporates emitter-common 7-channel. Refer to the pin connection diagram.
IC4	Assist motor driver	Switches the forward and reverse directions of the assist motor. Refer to the operation and function description of IC4 (BA6109).
IC5	Reel motor driver	Drives the reel motor, and switches between fast forward and rewind modes.
IC6	Playback equalizer amp	Has a gain of $A_v = 49.8\text{dB}$ (at 315Hz). This IC is also used for the KX-72R, 77OR and 727R.
IC8	Recording equalizer amp	IC AN6556 is used which has a higher slew rate.
IC9	3-pin regulator (+15V)	
IC11,IC12	Level meter driver	These are also used for the KX-6XC, 770R.

Reset circuit for the microcomputer

Since IC1 is a CMOS IC (μ PD7507C-099) and IC2 is an N-channel MOS IC (LM6417E-444), the reset signal detection mode is opposite in phase (180° out of phase) from each other, i.e., IC1 detects the high-to-low level change whereas IC2 detects the low-to-high level change.

For this reason, the reset signal for IC1 is phase-inverted by Q53, the output of which is coupled with the reset pin of IC2.

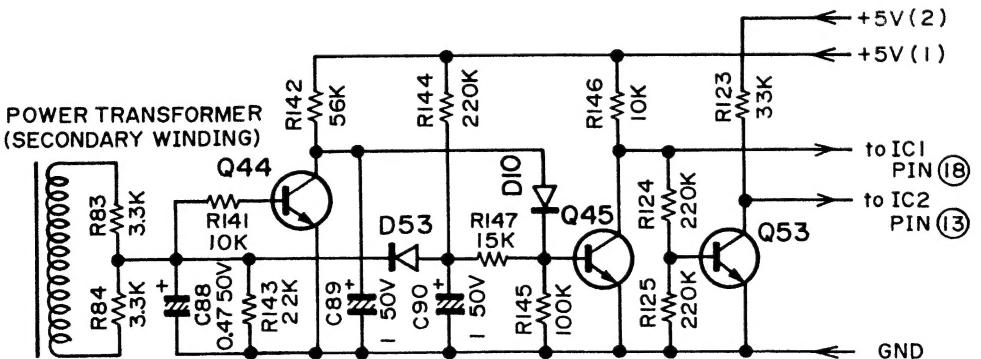
(When the power is on)

Since Q44 does not contribute to the reset operation, the same reset signal as that for the conventional models KX-6XC, 880 and 880SR is developed at the collector of Q45.

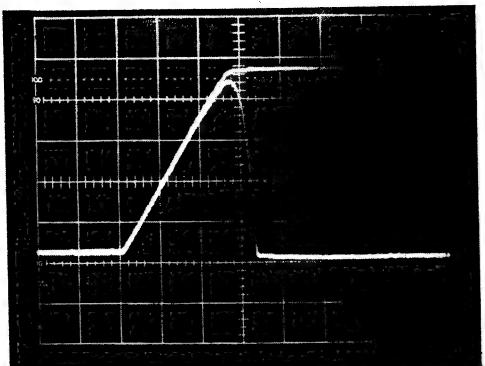
(When the power is off)

Immediately after the power is switched off, the base potential of Q45 is discharged through D53 with the result that Q45 turns off and that the collector potential of Q45 reaches +5V. In the case of the KX-790R, so that the mechanism reset is positively performed using the initialize command of the microcomputer when the power is switched off, the +5V potential is retained for some time by storing the charge at C77 (330μF).

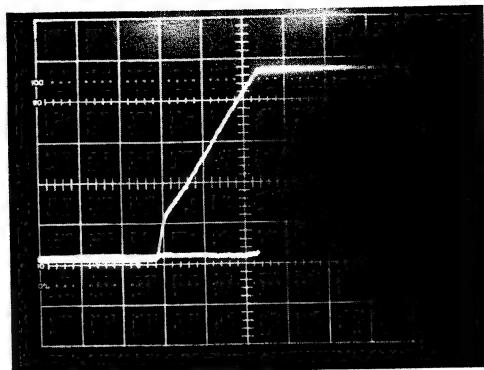
For this reason, after Q44 turns off, Q45 turns following the time constant given by R142 times C89 (following the timing delay given by multiplying R142 value by C89 value.) This permits the collector potential of Q45 to shift from high to low, providing the power off reset signal.



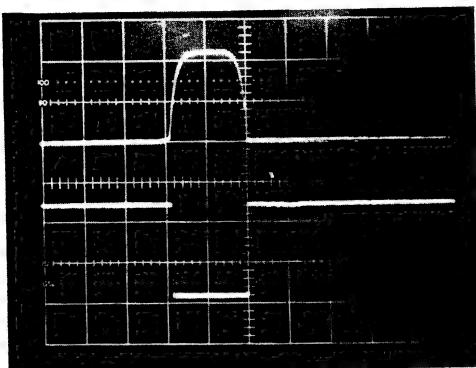
CIRCUIT DESCRIPTION



POWER ON
 { IC1 (pin 18)
 + 5V (1)
 (20ms/DIV)
 1V/DIV)



POWER ON
 { IC2 (pin 13)
 + 5V (2)
 (20ms/DIV)
 1V/DIV)



POWER OFF
 IC1 (pin 18)
 (5ms/DIV)
 2V/DIV
 IC2 (pin 13)

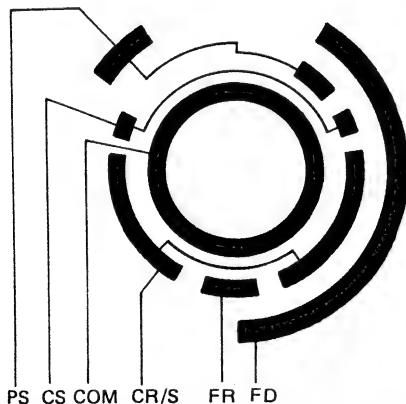
Mechanism timing chart

1. Operation

a. Position sensor

The switching timing of all operation is controlled by the position sensor.

FD	DIRECTION FORW
FR	FF/REW
CR/S	CUE RETURN/STOP
COM	COMMON
CS	CUE STOP
PS	PLAY STOP

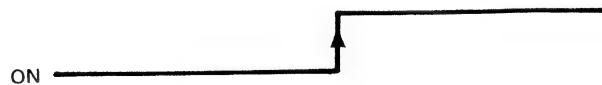


b. Position detection

Theoretically speaking, the position is detected in the same way for both the forward and reverse directions. The forward side has the detect pattern (FD) for detecting the direction. By means of this FD patterns, the direction of the assist motor is controlled.

2. Trigger point

The detect timing of the position sensor is performed by connecting to common. The operation change-over point is illustrated in the timing chart as follows.



CIRCUIT DESCRIPTION

MODE	OPERATION	STOP (F) → PLAY (F)	STOP (F) → FF (F)
	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

FD . . . DIRECTION FWD
 FR . . . FF/REW CS . . . CUE STOP
 CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	STOP (F) → REW (F)	STOP (F) → CUE (F)
	KEY ON			
Mechanism sensor (input)	FD 34 pin			
	FR 38 pin			
	CR/S 37 pin			
	CS 36 pin			
	PS 35 pin			
Assist motor (output)	FWD 16 pin			
	REV 17 pin			
Reel motor (output)	FF 14 pin			
	REW 15 pin			
	PLAY 28 pin			
Amplifier control (output)	LINE MUTE 13 pin			
	REC MUTE 11 pin			
	R/P 12 pin			
	BIAS 10 pin			

FD . . . DIRECTION FWD

FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE \ OPERATION	STOP (F) → RVW (F) (Review)	FF (F) → STOP (F)
KEY ON		
Mechanism sensor (input)	FD 34 pin	
	FR 38 pin	
	CR/S 37 pin	
	CS 36 pin	
	PS 35 pin	
Assist motor (output)	FWD 16 pin	
	REV 17 pin	
Reel motor (output)	FF 14 pin	
	REW 15 pin	
	PLAY 28 pin	
Amplifier control (output)	LINE MUTE 13 pin	
	REC MUTE 11 pin	
	R/P 12 pin	
	BIAS 10 pin	

FD . . . DIRECTION FWD
FR . . . FF/REW CS . . . CUE STOP
CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE	OPERATION	STOP(F)→PLAY(R)	PLAY(F)→STOP(F)
	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

FD . . . DIRECTION FWD

FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	PLAY (F) → CUE (F)	PLAY (F) → RVW (F) (Review)
	KEY ON			
Mechanism sensor (input)	FD 34 pin			
	FR 38 pin			
	CR/S 37 pin		70ms	70ms
	CS 36 pin		35ms	35ms
	PS 35 pin		15ms	40ms
Assist motor (output)	FWD 16 pin		35ms	35ms
	REV 17 pin		50ms	50ms
Reel motor (output)	FF 14 pin			15ms
	REW 15 pin			
	PLAY 28 pin		40ms	
Amplifier control (output)	LINE MUTE 13 pin			
	REC MUTE 11 pin			
	R/P 12 pin			
	BIAS 10 pin			

FD . . . DIRECTION FWD
 FR . . . FF/REW CS . . . CUE STOP
 CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

OPERATION		PLAY (F) → PLAY (R)	FF (F) → PLAY (F)
MODE			
	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

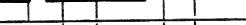
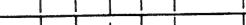
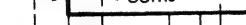
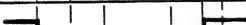
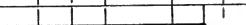
FD . . . DIRECTION FWD
FR . . . FF/REW CS . . . CUE STOP
CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

OPERATION		FF (F) → REW (F) → FF (F)	FF (F) → PLAY (R)
MODE			
	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

FD . . . DIRECTION FWD
 FR . . . FF/REW CS . . . CUE STOP
 CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	
		CUE (F) → STOP (F)	
		CUE (F) → PLAY (F)	
Mechanism sensor (input)	KEY ON		
	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
Assist motor (output)	PS 35 pin		
	FWD 16 pin		
Reel motor (output)	REV 17 pin		
	FF 14 pin		
	REW 15 pin		
Amplifier control (output)	PLAY 28 pin		
	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
BIAS 10 pin			

FD . . . DIRECTION FWD
FR . . . FF/REW CS . . . CUE STOP
CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE	OPERATION		STOP (R) → PLAY (F)
		CUE (F) → RVW (F) → CUE (F) (Review)	
	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

FD . . . DIRECTION FWD
FR . . . FF/REW CS . . . CUE STOP
CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	STOP (R) → FF (R)	STOP (R) → PLAY (R)
	KEY ON			
Mechanism sensor (input)	FD 34 pin			
	FR 38 pin		40ms	
	CR/S 37 pin		40ms	180ms
	CS 36 pin			35ms
	PS 35 pin			20ms
Assist motor (output)	FWD 16 pin		20ms	
	REV 17 pin			
Reel motor (output)	FF 14 pin			
	REW 15 pin			
	PLAY 28 pin			
Amplifier control (output)	LINE MUTE 13 pin			140ms
	REC MUTE 11 pin			
	R/P 12 pin			
	BIAS 10 pin			

FD . . . DIRECTION FWD

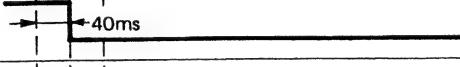
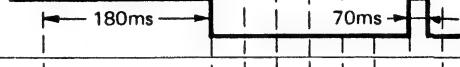
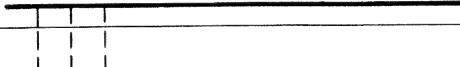
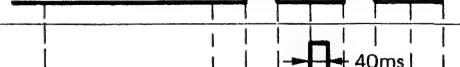
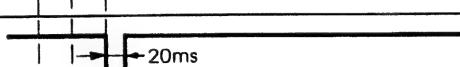
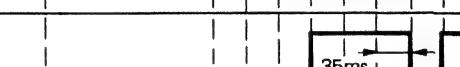
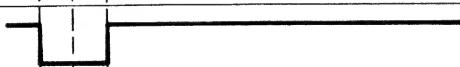
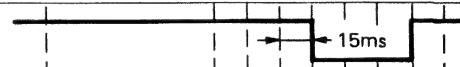
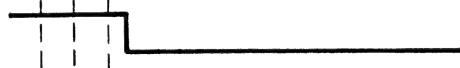
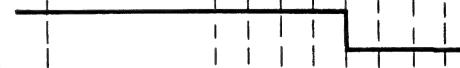
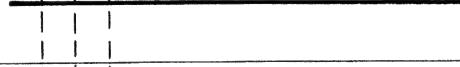
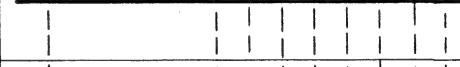
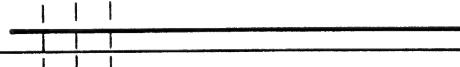
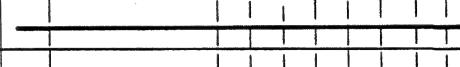
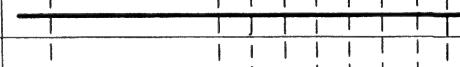
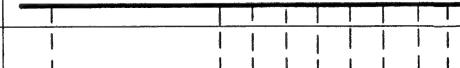
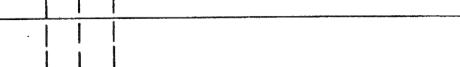
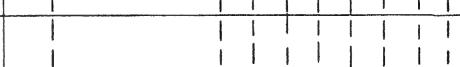
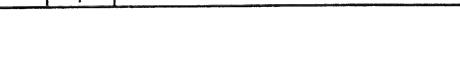
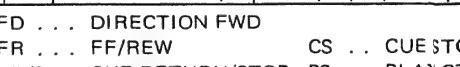
FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

PS . . . PLAY STOP

CIRCUIT DESCRIPTION

OPERATION		STOP (R) → REW (R)	STOP (R) → CUE (R)
MODE	KEY ON		
Mechanism sensor (input)	FD 34 pin		
	FR 38 pin		
	CR/S 37 pin		
	CS 36 pin		
	PS 35 pin		
Assist motor (output)	FWD 16 pin		
	REV 17 pin		
Reel motor (output)	FF 14 pin		
	REW 15 pin		
	PLAY 28 pin		
Amplifier control (output)	LINE MUTE 13 pin		
	REC MUTE 11 pin		
	R/P 12 pin		
	BIAS 10 pin		

FD . . . DIRECTION FWD

FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	STOP (R) → RVW (R) (Review)	FF (R) → STOP (R)
	KEY ON			
Mechanism sensor (input)	FD 34 pin			
	FR 38 pin			
	CR/S 37 pin			
	CS 36 pin			
	PS 35 pin			
Assist motor (output)	FWD 16 pin			
	REV 17 pin			
Reel motor (output)	FF 14 pin			
	REW 15 pin			
	PLAY 28 pin			
Amplifier control (output)	LINE MUTE 13 pin			
	REC MUTE 11 pin			
	R/P 12 pin			
	BIAS 10 pin			

FD . . . DIRECTION FWD
FR . . . FF/REW CS . . CUE STOP
CR/S . . CUE RETURN/STOP PS . . PLAY STOP

CIRCUIT DESCRIPTION

MODE	OPERATION	STOP (R) → PLAY (F)		STOP (F) → REC (F)	
	KEY ON				
Mechanism sensor (input)	FD 34 pin				
	FR 38 pin				
	CR/S 37 pin				
	CS 36 pin				
	PS 35 pin				
Assist motor (output)	FWD 16 pin				
	REV 17 pin				
Reel motor (output)	FF 14 pin				
	REW 15 pin				
	PLAY 28 pin				
Amplifier control (output)	LINE MUTE 13 pin				
	REC MUTE 11 pin				
	R/P 12 pin				
	BIAS 10 pin				

FD . . . DIRECTION FWD

FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

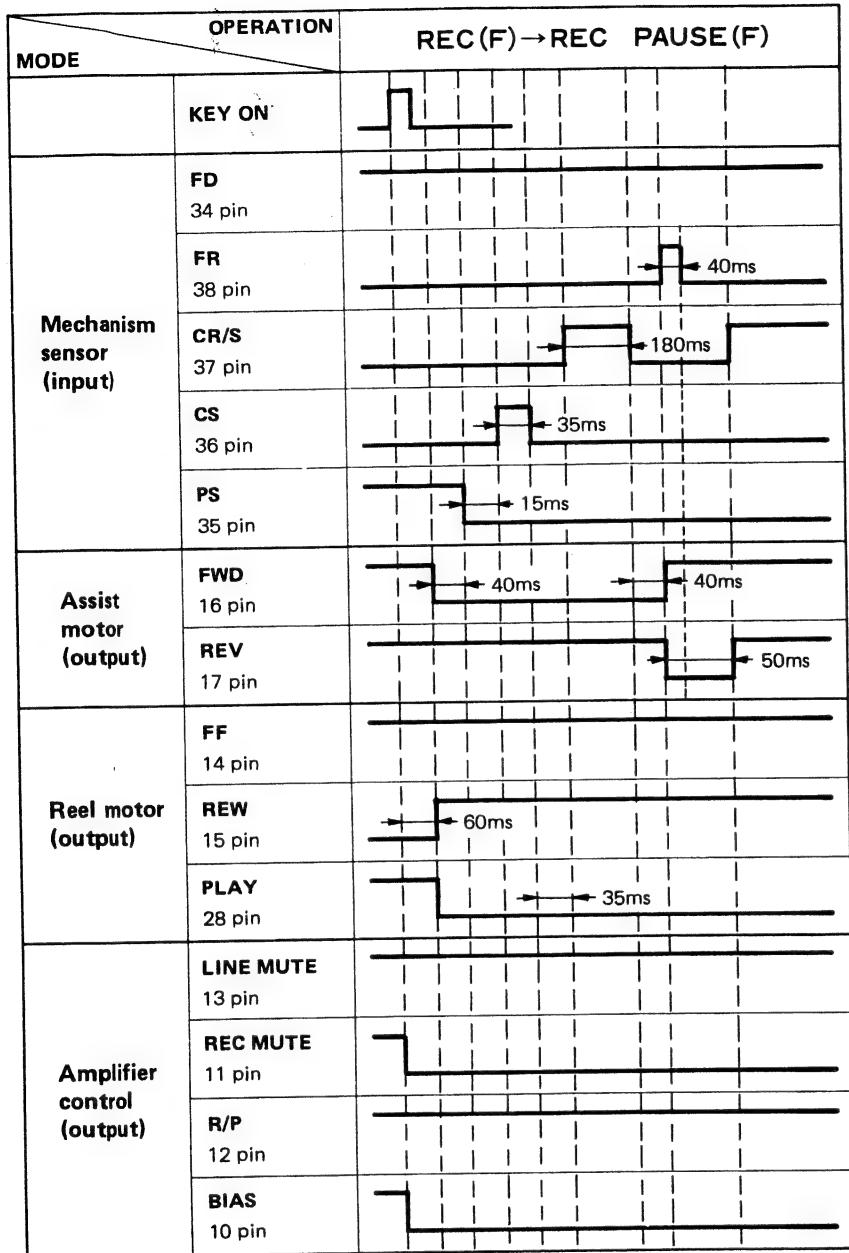
PS . . . PLAY STOP

CIRCUIT DESCRIPTION

MODE		OPERATION	STOP (F) → REC	PAUSE (F)	REC	PAUSE (F) → STOP (F)
	KEY ON					
Mechanism sensor (input)	FD 34 pin					
	FR 38 pin		70ms			40ms
	CR/S 37 pin		50ms			50ms
	CS 36 pin					
	PS 35 pin					
Assist motor (output)	FWD 16 pin		40ms			40ms
	REV 17 pin		40ms			40ms
Reel motor (output)	FF 14 pin					
	REW 15 pin					
	PLAY 28 pin					
Amplifier control (output)	LINE MUTE 13 pin		140ms			
	REC MUTE 11 pin					
	R/P 12 pin					
	BIAS 10 pin					

FD . . . DIRECTION FWD
FR . . . FF/REW CS . . . CUE STOP
CR/S . . . CUE RETURN/STOP PS . . . PLAY STOP

CIRCUIT DESCRIPTION



FD . . . DIRECTION FWD

FR . . . FF/REW

CS . . . CUE STOP

CR/S . . . CUE RETURN/STOP

PS . . . PLAY STOP

DESCRIPTION OF MECHANISM OPERATION

Operation of 3-motor 2-way Record/Play Cassette Deck Mechanism

This cassette deck mechanism, one of the logic control auto-reverse mechanism series, has three motors: the capstan motor to drive the capstans in two ways, the reel motor to drive the reels and the mode control motor to set the operation modes such as play mode, rewind mode, etc.

Thus, as these three exclusive motors are used with their respective separate roles in driving the tape feed mechanism, many levers and other devices needed in conventional

tape feed mechanisms are omitted, thus permitting a greatly simplified mechanism with higher operational reliability, lower failure rate and easier maintenance.

In addition, as this cassette deck mechanism performs all operation mode controls entirely electrically, operability is excellent, permitting all logic operations including auto-reverse, remote control, etc.

The basic construction for feeding the tape consists of the following three sections :

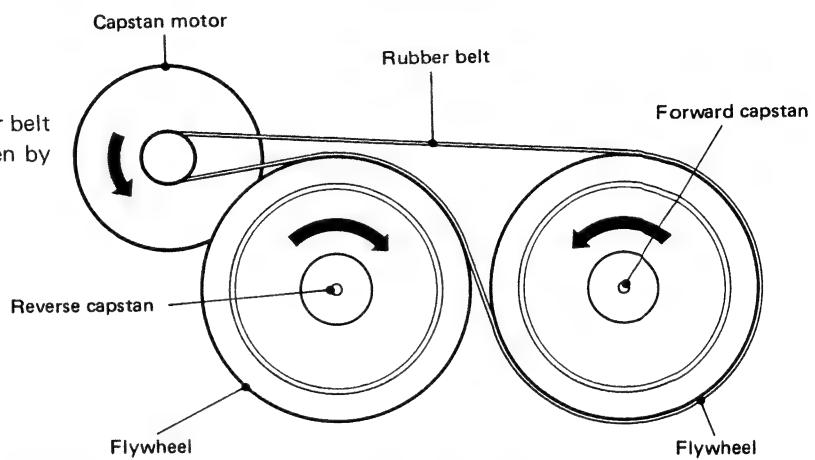


Fig. 1

1. Capstan drive system

The forward and reverse capstans which have a rubber belt on their respective flywheels in an S shape are driven by the exclusive capstan motor.

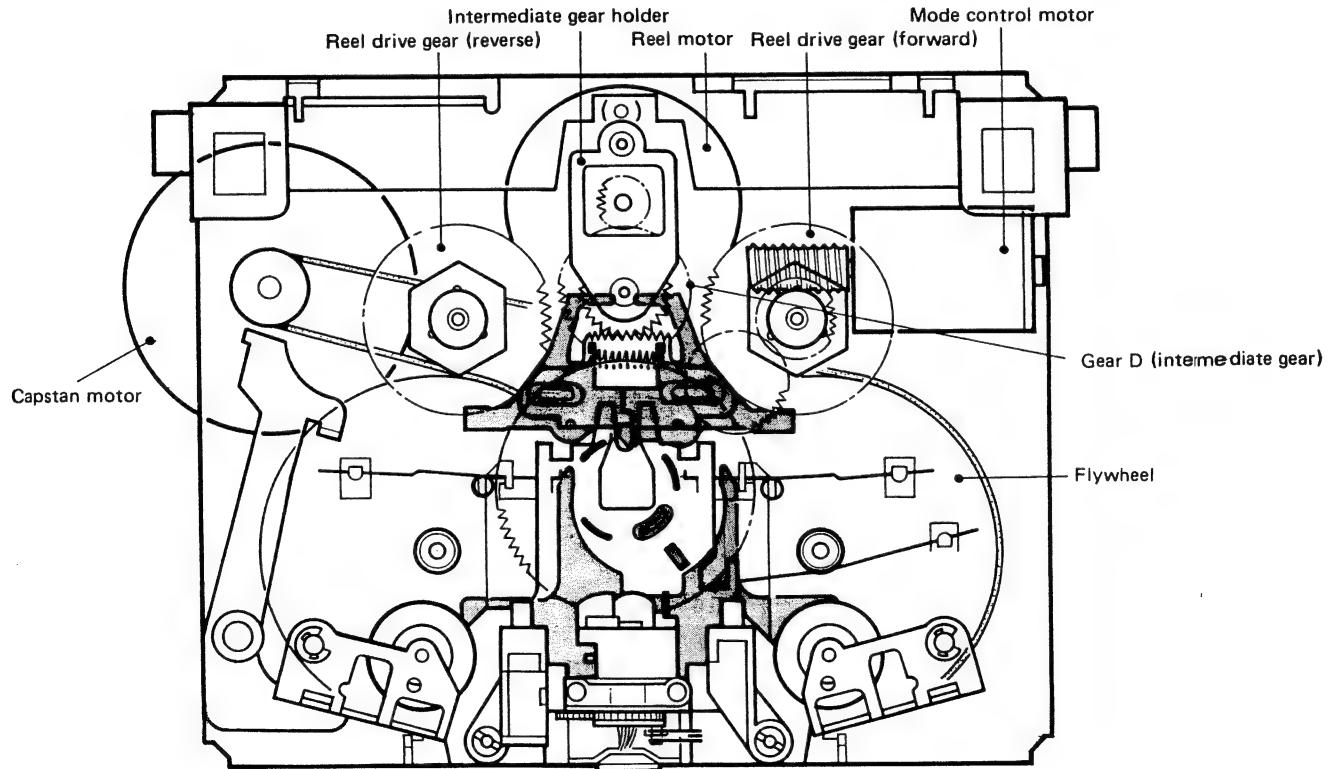


Fig. 2 (surface view)

DESCRIPTION OF MECHANISM OPERATION

2. Reel drive system

The reel at the takeup side is driven by the relevant reel drive gear which engages the intermediate gear by the rotating force generated in the rotating direction of the exclusive reel motor; the intermediate gear engages with the gear mounted to the reel motor shaft and it can move freely to the right and left.

The rotating direction of the reel motor is changed by changing the polarity of the motor applied voltage and the travel speed of the tape (in play or fast forward mode, etc.) is controlled by changing the motor applied voltage.

3. Mode control system

The rotation of the mode control motor is decelerated by the worm gear to rotate the cam disc plate. The first cam to control the direction of the rotary head and the second cam to set an operation mode such as play, fast forward, cue, etc. are placed under the cam disc plate. The four leaf contacts located above the cam disc plate come in contact with the conductor code patterns which correspond to the operation modes.

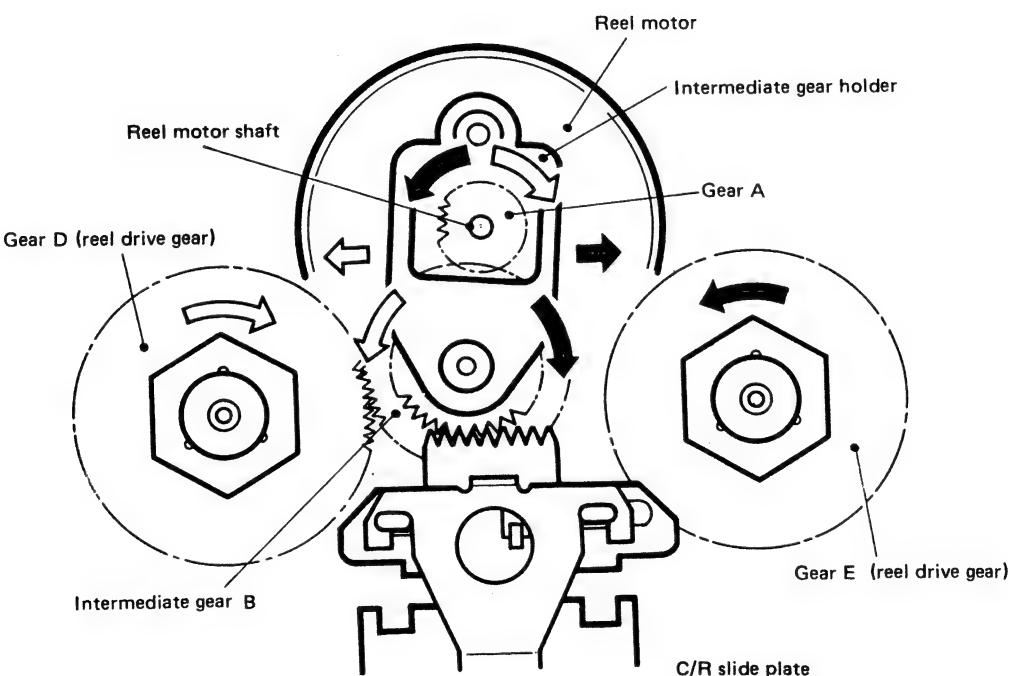
As the cam disc plate rotates, the relative position between the conductor code patterns and the leaf switch contacts varies so that a combination voltage, i.e. a mode code, appears in the output terminal on a code pattern.

At input of this combination voltage, the controller judges that the cam disc plate turns to the position of the required operation mode. The operation mode is thus controlled.

Next, the basic operation of the tape feed mechanism.

A variety of usages are possible according to the programming of the controller as the mechanism construction permits all operation modes to be controlled electrically.

The following description gives provisional explanatory examples for basic operation.



DESCRIPTION OF MECHANISM OPERATION

A. Stop (forward) mode

Fig. 3a represents the cam drive system in mode control as viewed from the rear of the deck and Fig. 3b indicates the cassette mechanism as viewed from above.

- 1) The brake cam is placed under gear D as shown in Fig. 3a. Thus, as the top end of the brake lever engages the a reel drive gear with the triangular protrusion of a brake lever in the concave of a brake cam, the reel drive gear is prevented from rotating and the reel is braked.
- 2) The first cam is placed under the cam disc plate as shown in Fig. 3a. In this cam disc plate position, the

rotary head is set at the forward record/play position with the rotary head direction selector slide plate shifted to the left.

- 3) The second cam is positioned as shown in Fig. 3a. At this time, the drive catch of the forward pinch roller slide base is in contact with the left top end of the second cam as shown in Fig. 3b. In this state of the drive catch, the rotary head and the pinch roller (forward) recede out of contact with the tape with the pinch roller slide base (forward) and the head base lowered.

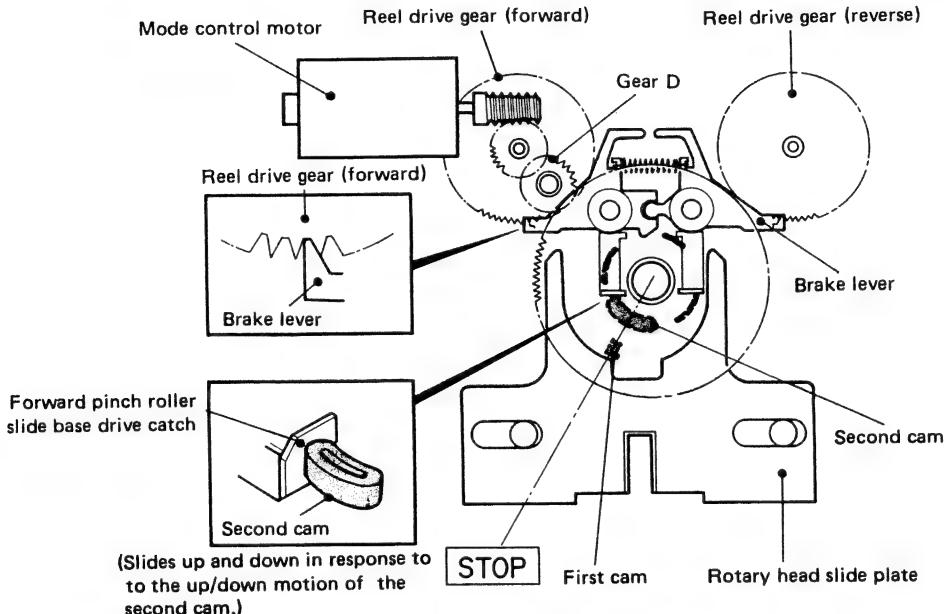


Fig. 3a (rear view)

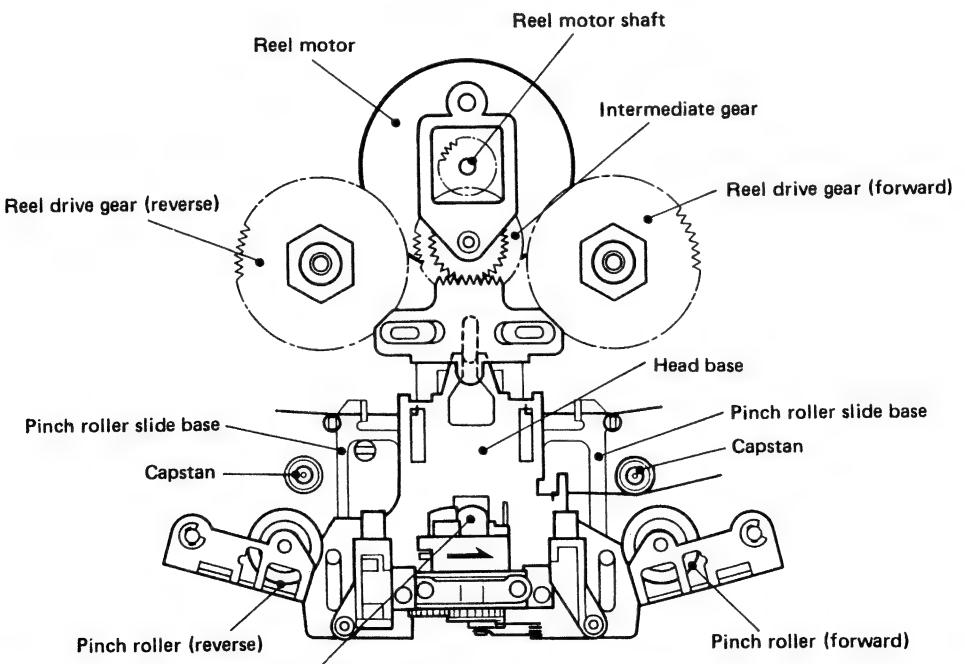


Fig. 3b (surface view)

DESCRIPTION OF MECHANISM OPERATION

B. Fast forward (FF) mode

- 1) When the FF button is pressed, the controller drives the mode control motor to rotate the cam disc plate in the direction of the arrow in Fig. 4a.
- 2) Thereby, the brake cam turns slightly clockwise and lifts up the triangular protrusion of the brake so that the brake is released as shown in Fig. 4a.
- 3) In addition, when the cam disc plate turns to the position shown in Fig. 4a, the fast forward (FF) mode code is generated by its associated code pattern.

When the controller detects this code, it issues an instruction to stop the voltage applied to the mode control motor. Thereby, the mode control motor stops. The fast forward (FF) mode is established in this manner.

- 4) Since the second cam on the cam disc plate turns counterclockwise, the position of the pinch roller slide base drive catch (forward) does not change. Therefore, the head and the pinch roller remain lowered.
- 5) When the controller detects the fast forward mode, it issues an instruction to supply to the reel motor a high voltage whose polarity corresponds to fast forward mode so that the reel motor rotates at high speed in the forward direction. By this rotation, the intermediate gear is moved to the right and engaged with the reel drive gear (forward) at the right side. Thus, the tape travels in fast forward mode.

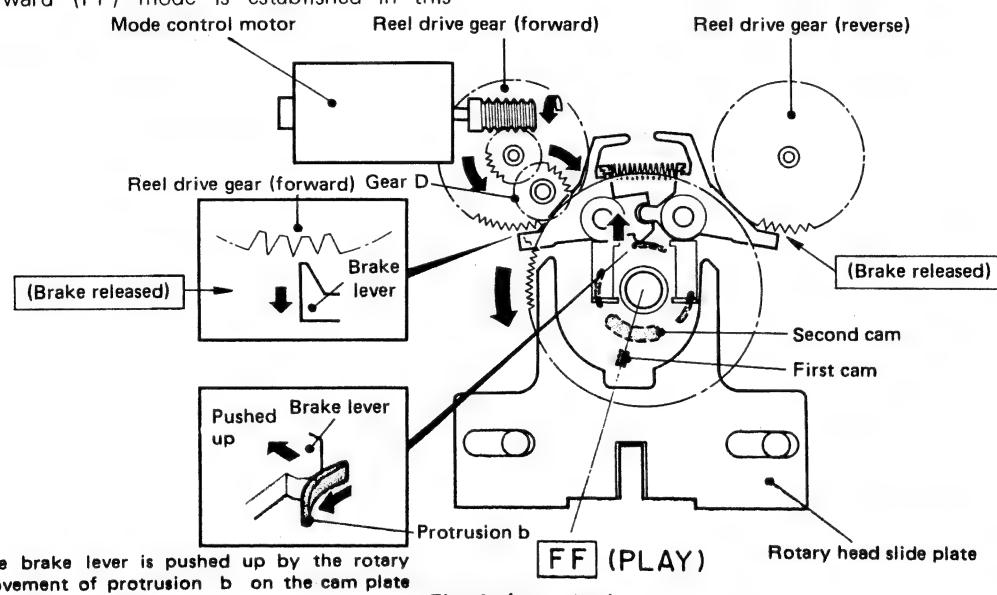


Fig. 4a (rear view)

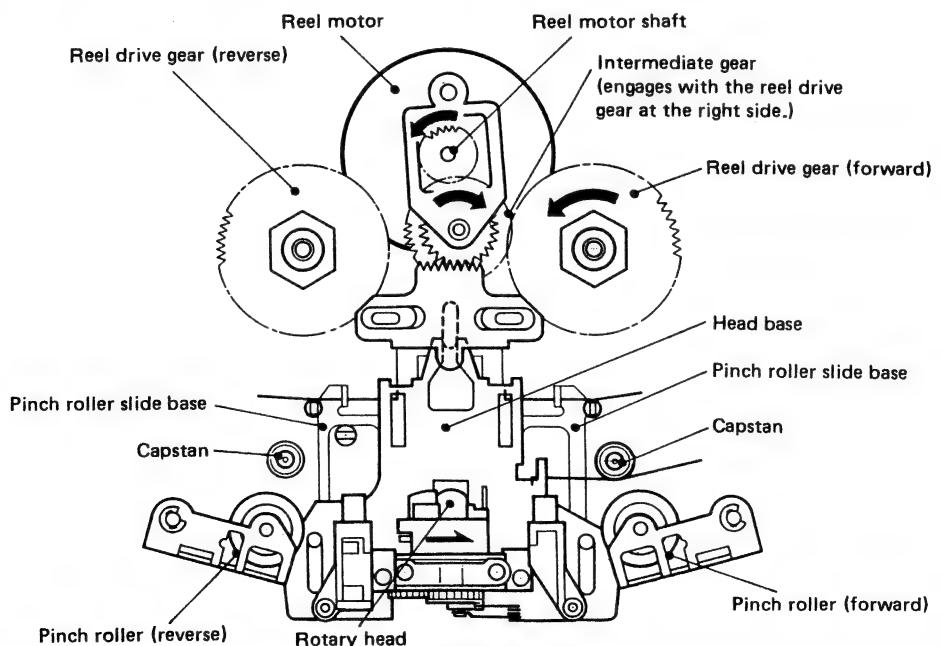


Fig. 4b (surface view)

DESCRIPTION OF MECHANISM OPERATION

C. Play (forward) mode

- 1) When the play button is pressed, the controller issues an instruction to turn the cam disc plate in the direction of the arrow as shown in Fig. 5a.
- 2) Thereby, the second cam on the cam disc plate pushes up the drive catch of the forward pinch roller slide base (right). When the cam disc plate turns to the position shown in Fig. 5a, the play (forward) mode code is generated by its associated code pattern. When the controller detects this code, it works to stop the mode control motor.
- 3) In this cam position,
 - a) As the brake cam is at the non-braking position as shown in Fig. 5a, the brake is released.

b) As the drive catch of the forward pinch roller slide base (right) moves to the uppermost (play) position, the pinch roller (forward) comes up in contact with the capstan. At this time, the head base slides up in response to the motion of the pinch roller so that the head comes in contact with the tape.

c) The controller designates the polarity and voltage of the power required for the reel motor in play (forward) mode and issues an instruction to supply it to the reel motor.

Thereby, the reel motor rotates in the forward direction on the voltage corresponding to play mode. By this rotation, the intermediate gear is moved to the right and engaged with the reel drive gear (forward) at the right side. Thus, the tape travels in play (forward) mode.

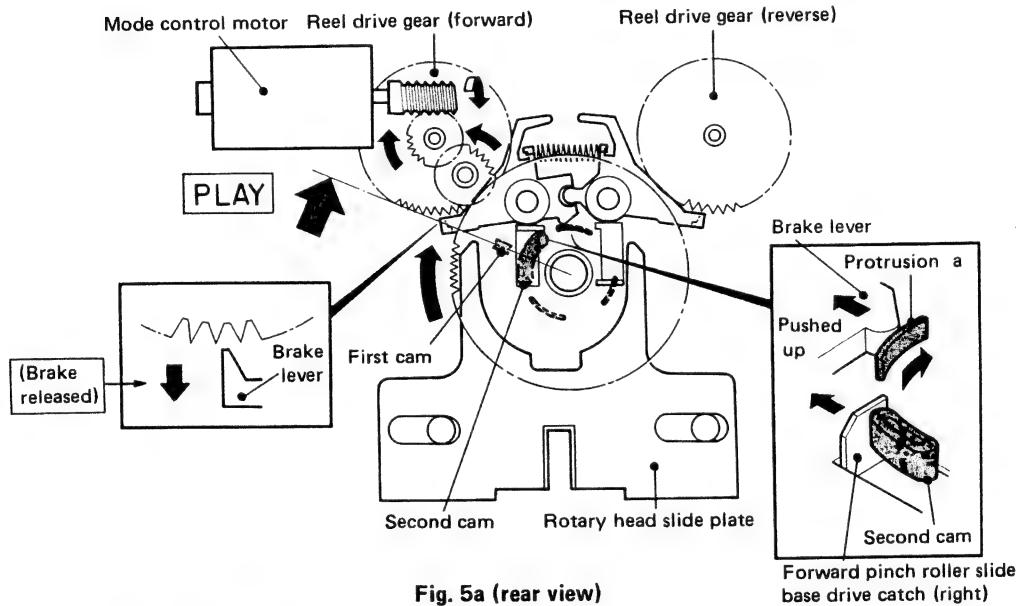


Fig. 5a (rear view)

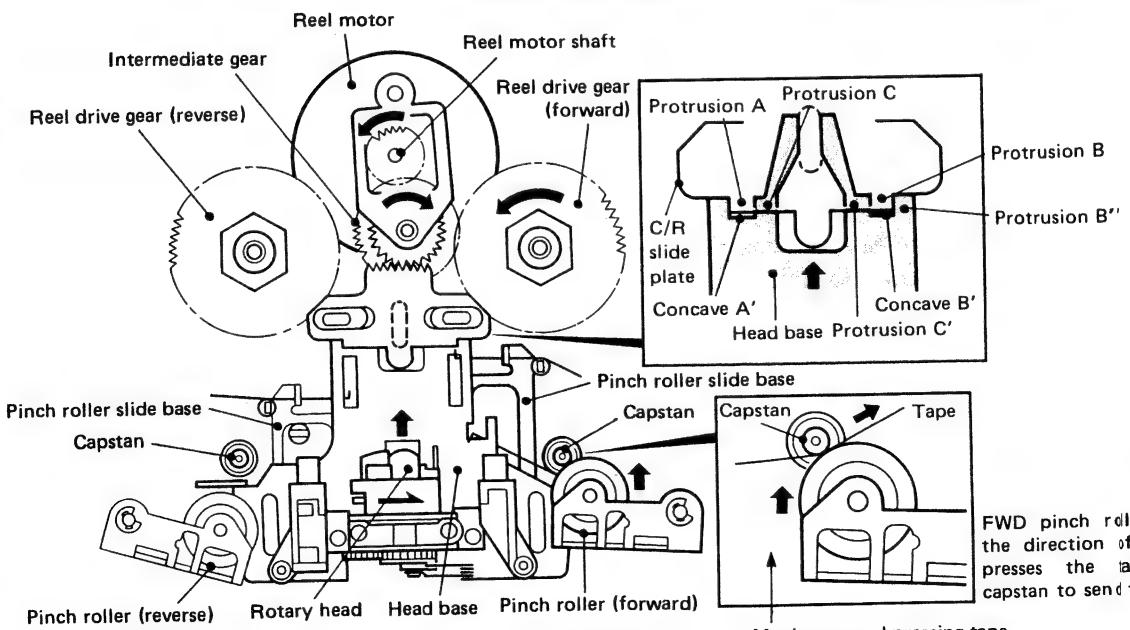


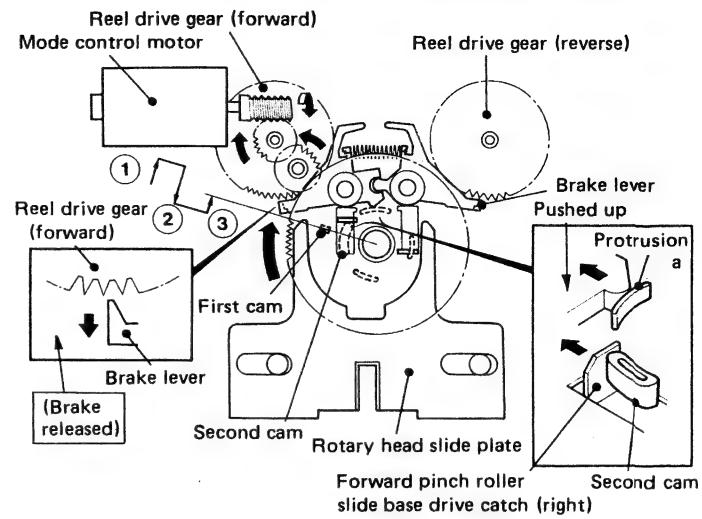
Fig. 5b (surface view)

FWD pinch roller moves up in the direction of the arrow and presses the tape against the capstan to send the tape forward.

DESCRIPTION OF MECHANISM OPERATION

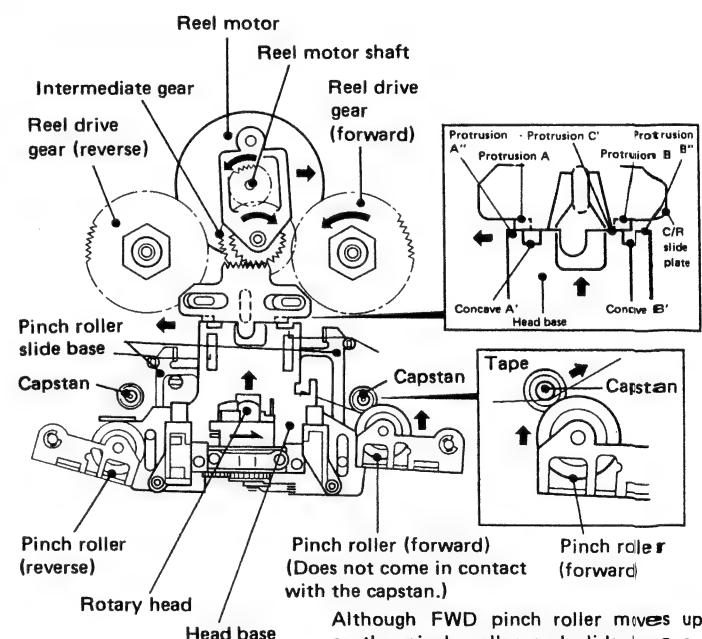
D. Cue mode

- 1) when the cue button is pressed in stop mode, the controller works to rotate the mode control motor to turn the cam disc plate in the direction of the arrow as shown in Fig. 6a. When the second cam on the cam disc plate pushes up the drive catch of the forward pinch roller slide base (right), the pinch roller (forward) and the rotary head move up correspondingly.
- 2) As the triangular protrusion of the brake lever comes in contact with the brake cam at its upper position, the brake is released.
- 3) the cam disc plate turns to the play position once. (Thus, the head and the pinch roller (forward) also move to their play position once.) When the cam disc plate reaches the play position, the controller issues an instruction to reverse the rotation of the mode control motor. When the cam disc plate thus turns reversely and stops at the position which is slightly lower than the cue position shown in Fig. 6a, the controller issues an instruction to rotate the reel motor at high speed in the forward direction.
- 4) When the reel motor is rotated at high speed in the forward direction, the intermediate gear is moved to the right and engaged with the reel drive gear (forward) so that the tape travels in cue mode. In this state of the mechanism, as the head base is at a position slightly lower than the play position because of the reverse rotation of the cam disc plate, protrusions A and B under the C/R slide plate are released from concaves A' and B' in the head base (in play mode, protrusions A and B are secured in concaves A' and B' to prevent the C/R slide plate deviating to the right and left) so that the C/R slide plate is free. Thus, the C/R slide plate moves to the left due to the rotation of the reel motor.
- 5) At the same time the C/R slide plate moves to the left, a pulse voltage is again supplied to the mode control motor to turn the cam disc plate clockwise. Thereby, the head base slides up again in response to the drive catch of the forward pinch roller slide base (right). At this time, since protrusions A and B in the C/R slide plate have already been shifted to the left, they cannot engage with concaves A' and B' in the head base. Therefore, top ends A'' and B'' of the head base strike protrusions A and B in the C/R slide plate to stop the up motion of the head base for cue mode.
- 6) In this state of the mechanism, the pinch roller (forward) is slightly away from the capstan and the head is at a position at which it is in light contact with tape. Thus, when the tape travels at high speed, a recording signal is played back as a high-pitched sound. In addition, the pinch roller slide base (right) moves to a position slightly higher than the position at which the head base stops, and presses against the head base upwards by the spring.



Protrusion a fixed to the cam plate and the second cam move up according to the rotation of the cam plate, but they are fixed at position (3) shown above.

Fig. 6a (rear view)



Although FWD pinch roller moves up as the pinch roller and slide base on FWD side move up, the pinch roller and capstan do not pinch the tape because of the relationship among position 3) indicated by the arrow in Fig. 6a Cueing Operation (Rear view) and protrusions and concaves of C/R slide plate and head base.

Fig. 6b (surface view)

DESCRIPTION OF MECHANISM OPERATION

E. Play (reverse) mode

- 1) When the play (reverse) button is pressed from forward stop mode, the controller works to rotate the mode control motor so that the cam disc plate turns counterclockwise from the stop position in Fig. 3a.
- 2) The first and second cams on the cam disc plate also turn. At this time, the first cam slides the rotary head direction selector slide plate to the right. Thereby, the rotary head turns 180° to the reverse play position. (See "K. Section of rotary head direction".)
- 3) On the other hand, the second cam pushes up the drive catch of the reverse pinch roller slide base (left). When the cam disc plate turns to the position in Fig. 7a, the play (reverse) mode code is generated by its associated code pattern. Thus, when the controller detects this code, it acts to stop the mode control motor.

- 4) In this cam position,
 - a) As the brake cam is at the no-braking position as shown in Fig. 7a, the brake is released.
 - b) As the drive catch of the reverse pinch roller slide base (left) moves to the uppermost (play) position, the pinch roller (reverse) comes up in contact with the capstan (Fig. 7b). At this time, the head base slides up in response to the motion of the reverse pinch roller slide base so that the head comes in contact with the tape.
 - c) The controller designates the polarity and voltage of the power required for the reel motor in play (reverse) mode and issues an instruction to supply it to the reel motor. Thereby, the reel motor rotates in the reverse direction on the voltage corresponding to play mode. By this rotation, the intermediate gear is moved to the left and engaged with the reel drive gear (reverse) at the left side. Thus, the tape travels in play (reverse) mode.

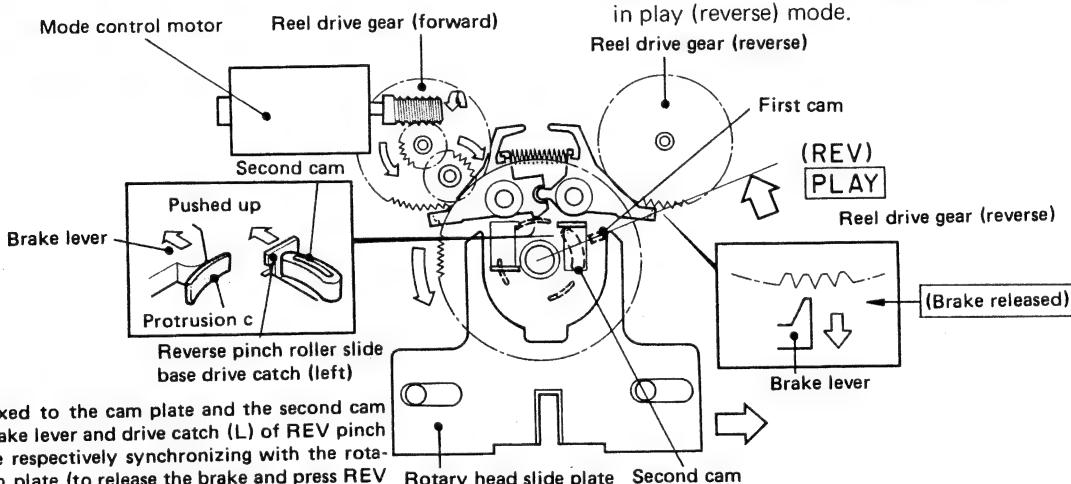


Fig. 7a (rear view)

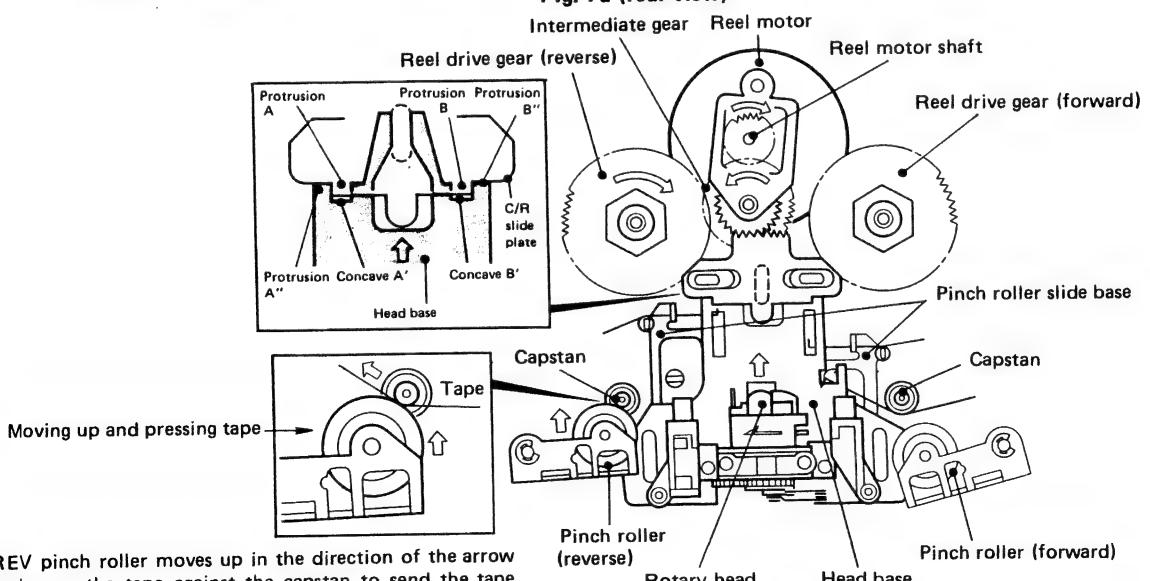


Fig. 7b (surface view)

DESCRIPTION OF MECHANISM OPERATION

F. Stop (reverse) mode

- 1) When the stop button is pressed from reverse play mode, the controller works to rotate the mode control motor so that the cam disc plate turns clockwise. The controller also acts to stop the reel motor.
- 2) The second cam on the cam disc plate turns downwards. Thereby, as the drive catch of the reverse pinch roller slide base descends, the pinch roller (reverse) and the head base also descend. When the cam disc plate thus comes to the stop position in Fig. 8a, the stop (reverse) mode code is generated by its associated code pattern. When the controller detects this code, it acts to stop the mode control motor.
- 3) At this time, the brake cam turns and engages with the triangular protrusion of the brake at its lower position. Thus, the reel drive gear (reverse) is braked so that the reel stops suddenly.

G. Pause mode

Description is omitted as it is mechanically the same as stop mode.

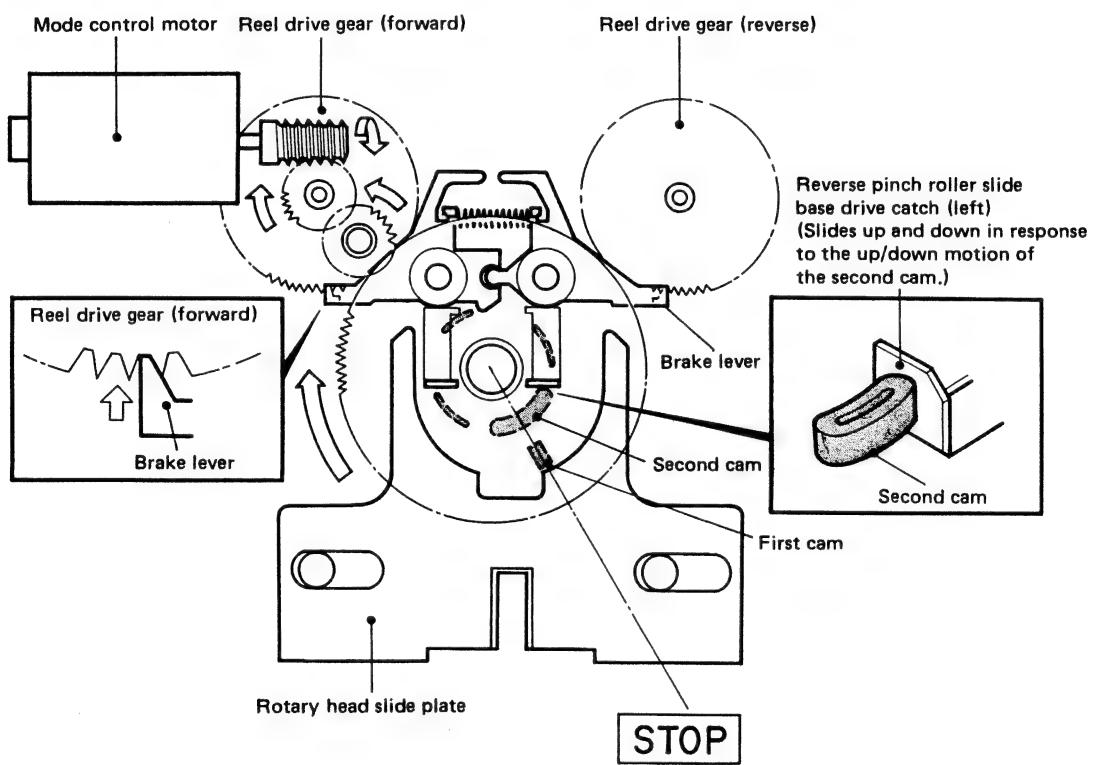


Fig. 8a (rear view)

DESCRIPTION OF MECHANISM OPERATION

H. Rewind (REW) mode

- When the rewind (REW) button is pressed from reverse stop mode, the cam disc plate turns clockwise to the rewind position. At this time, the rewind mode code is generated by its associated code pattern, indicating that the rewind mode is established. When the controller detects this code, it works to stop the mode control motor.
- In this state of the mechanism, the brake cam turns in the direction of the arrow in Fig. 9a to release the brake.

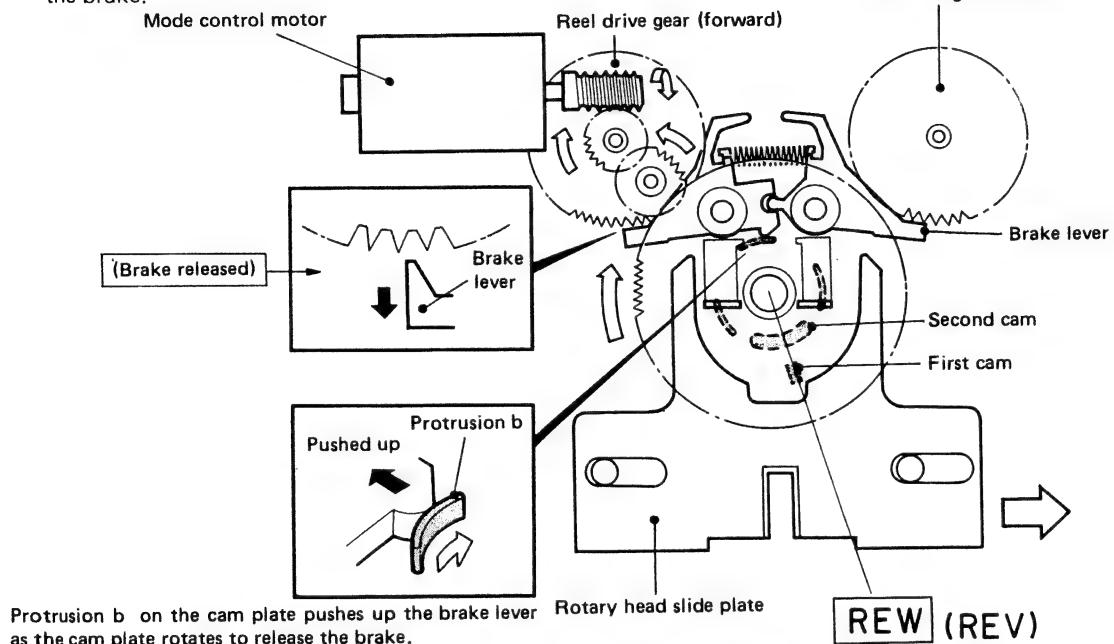


Fig. 9a (rear view)

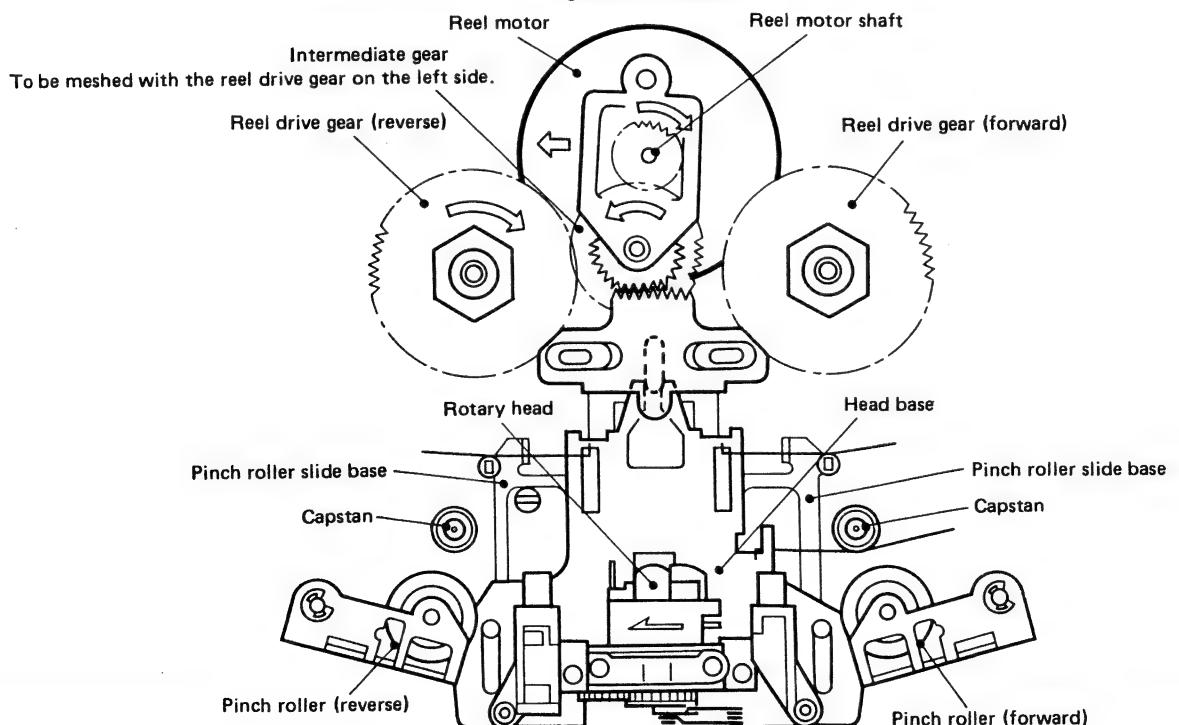


Fig. 9b (surface view)

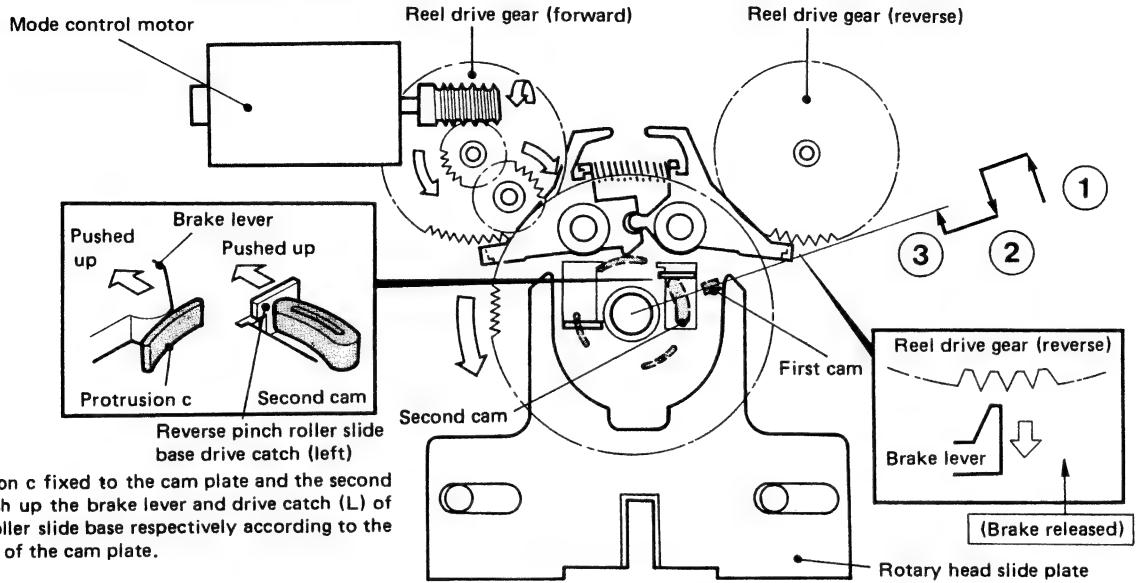
DESCRIPTION OF MECHANISM OPERATION

I. Review (cue) mode

1) The review operation reverses the forward direction of the tape. In this way, the review operation is just the same as the cue operation, except that in the review operation, the reverse pinch roller is raised near to the reverse capstan, the left reel drive gear is driven by moving the intermediate gear to the left, and the C/R slide plate, the first and second cams, etc. are moved

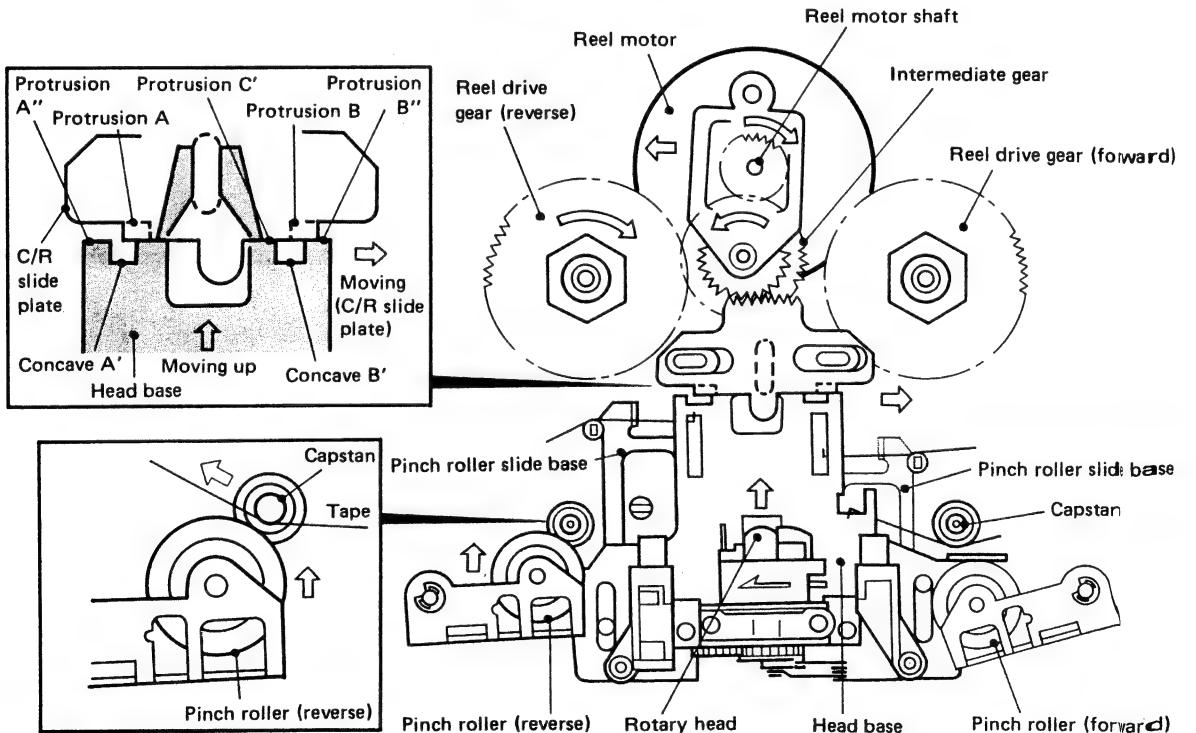
to the right, in contrast with the cue operation.

However, the turning of the rotary head and the review operation of the mechanism are performed separately. For this purpose, it is necessary to set up logic so that the rotary head also turns to the review position automatically when the review (REV) button is pressed. This also applies to the cue operation.



Protrusion c fixed to the cam plate and the second cam push up the brake lever and drive catch (L) of pinch roller slide base respectively according to the rotation of the cam plate.

Fig. 10a (rear view)



As REV pinch roller slide base moves up, REV pinch roller is moved up and fixed to positions (1)–(3) indicated by the arrows in Fig. 10a Review Operation (Surface view). This operation is carried out to perform the review operation without fitting the protrusion into the concave according to the relationship between the head base and C/R slide plate.

Fig. 10b (surface view)

DESCRIPTION OF MECHANISM OPERATION

J. Direct mode change operation

The respective modes at items A~I are described mainly based on stop mode. However, the mode can be changed directly from forward play to reverse play, etc. without going via stop mode. As mentioned before, the controller always knows the current operation mode of the mechanism by checking the output of a relevant code pattern.

Therefore, the mode can be changed in the shortest operation route from the current mode to the required mode, whatever it is, by programming the controller.

For example, assume the mode is to be changed from fast forward mode to rewind mode. At this time, the controller knows that the head and the pinch roller (forward) are lowered in fast forward mode at present. Thereupon, when the controller is programmed so as to stop the mode control motor once, brake the reel drive gear (forward), move the cam disc plate to the rewind position by rotating the mode control motor again, and reverse the rotation of the reel motor, the intermediate gear is automatically moved to the left to engage with the reel drive gear (reverse) at the left to enter rewind mode.

In due course, it is possible to change directly from one mode to any other mode through a similar process. As tens of combinations of mode changes can be set, further description is omitted here.

K. Selection of rotary head direction

- 1) The rotary head slide plate is slid to the left by turning the first cam on the cam disc plate clockwise (or to the right by turning counterclockwise.) Then, the rotary head direction selector lever is moved to the left (or right) by the slit provided on the rotary head slide plate, by which the direction of the rotary head is changed. In detail, as shown in Fig. 12, when the rotary head slide plate is slid to the right, the top end of the rotary head direction selector lever is moved to the right by the slit on the rotary head slide plate. Gear A thereby turns counterclockwise. Thus, the rotary head engaged with this gear turns 180° to the forward record/play position.
- 2) When the rotary head is to be set to the reverse record/play position, the rotary head slide plate is slid to the left.
- 3) The spring provided provides a snap action to set the head to the correct position at any time.

L. Tape end sensor mechanism (auto-stop, quick reverse, etc.)

To detect the tape end, a quick sensor consisting of an LED and a photocell is installed at the left side. This quick sensor is constructed as shown in Fig. 11.

In this construction, the light emitted from the LED strikes the tape through an optical fiber, and the reflection light is directed into the photocell through another optical fiber. When the magnetic section of the tape passes the optical fibers, as the emission light is absorbed, no output of the photocell is obtained. On the other hand, when the non-magnetic opaque white or transparent leader tape section near the tape end passes the optical fibers, as the reflection light from this section or the reflector plate (located after the tape) is input to the photocell (Fig. 11 shows the case of the transparent type), the output of the photocell starts. This output is input to the controller for various applications such as auto-stop, auto-reverse, repeat play, etc. (The controller already knows which side of the tape is the tape end by checking the mode code pattern output.)

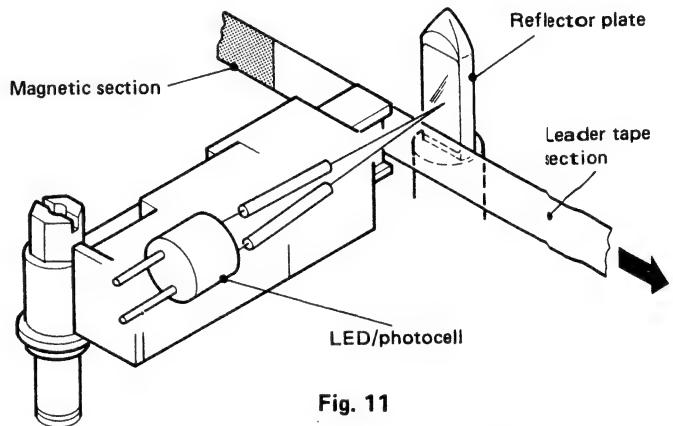


Fig. 11

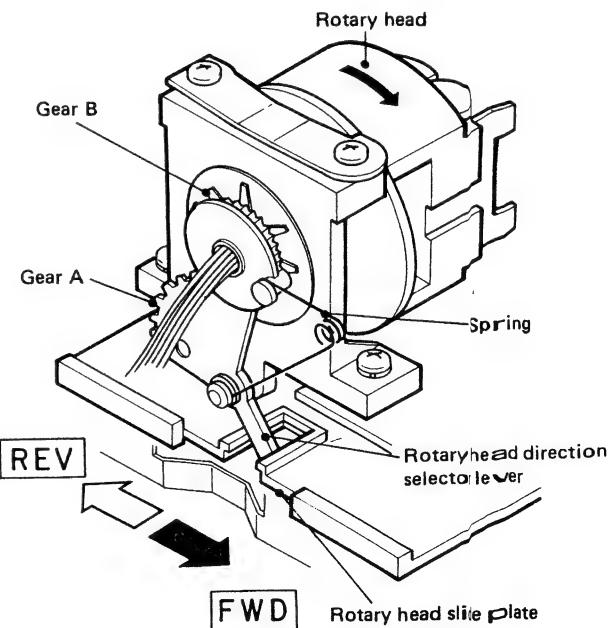
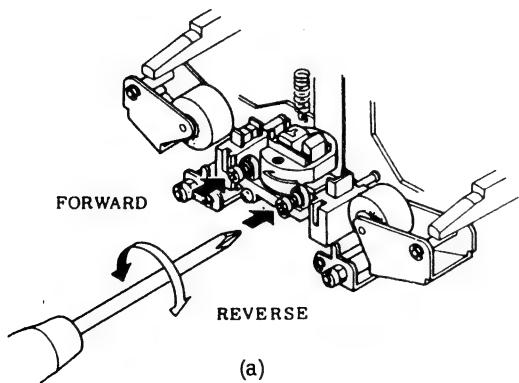


Fig. 12

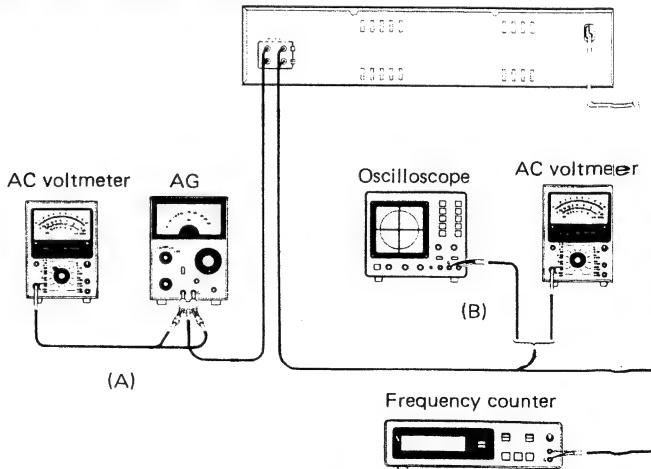
ADJUSTMENT

No.	ITEM	INPUT SETTINGS	OUTPUT SETTINGS	CASSETTE TAPE DECK SETTINGS	ALIGNMENT POINTS	ALIGN FOR	FIG.
CASSETTE DECK SECTION TAPE: NORMAL, DOLBY: OFF, INPUT: LINE, OUTPUT/PHONES LEVEL: MAX						0dBs=0.775V	
I REC/PLAY HEAD							
[1]	DEMAGNETIZATION	—	—	POWER: OFF Remove the cassette door.	REC/PLAY head	Demagnetize the REC/PLAY head with a head demagnetizer.	
[2]	CLEANING	—	—	POWER: OFF Remove the cassette door.	REC/PLAY head erase head, capstan and pinch roller.	Clean the REC/PLAY head erase head, capstan and pinch roller using a cotton swab slightly damped with alcohol.	
[3]	AZIMUTH	MTT-256 10kHz, -20dB	(B)	PLAY	Azimuth adjustment screw	Adjust the azimuth adjustment screw so that the output voltage is maximized in both forward and reverse direction.	(a)
II DC MOTOR							
(i)	TAPE SPEED	MTT-111 MTT-111D	(B)	PLAY	Trimming potentiometer in the DC motor	Adjust the tape speed so that a 3kHz signal is produced at the center of the tape.	
III PC BOARD							
< 1 >	PLAYBACK LEVEL	MTT-256 315Hz, 0dB	(B)	PLAY	VR3 (L) VR4 (R)	Output level: -6.0dBs (390mV)	
< 2 >	BIAS CURRENT	(A) 1kHz, -30dBs 10kHz, -30dBs	(B)	Adjust REC and BALANCE so that the REC monitor output becomes -26dBs at 1kHz, then record and reproduce signal of 1kHz and 10kHz in alternation.	VR7 (L) VR8 (R)	Record 1kHz and 10kHz in alternation and adjust the variable resistors which control the bias current so that the same playback level is obtained.	
< 3 >	RECORD LEVEL	(A) 1kHz, -30dBs	(B)	Record and reproduce a 1kHz signal under the conditions set in < 2 >.	VR5 (L) VR6 (R)	Adjust the variable resistors so that a playback level of -26dBs (39mV) is obtained.	

AZIMUTH ADJUSTMENT SCREW



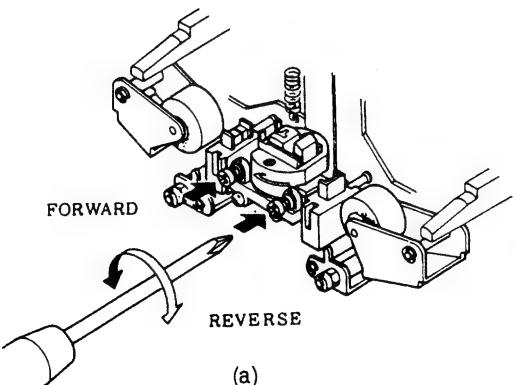
SYSTEM CONNECTIONS



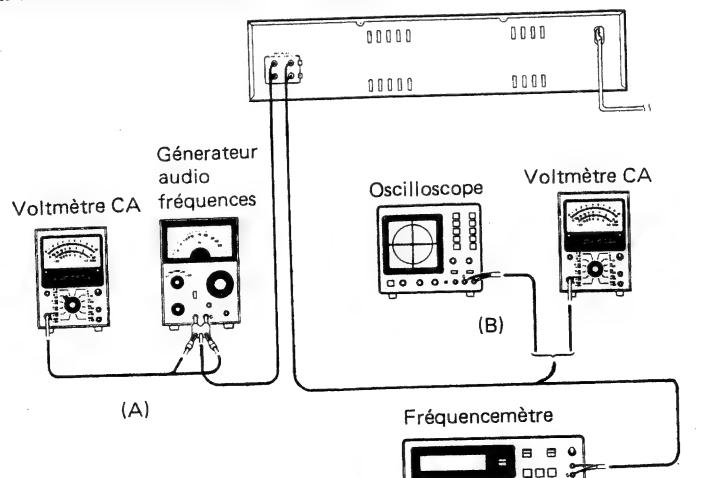
REGLAGE

N°	ITEM	REGLAGE DE L'ENTREE	REGLAGE DE LA SORTIE	REGLAGE DU MAGNETO -PHONE A CASSETTE	POINTS DE L'ALIGNEMENT	ALIGNER POUR	FIG.
SECTION DU MAGNETOPHONE							
TAPE: NORMAL, DOLBY: OFF, INPUT: LINE, OUTPUT/PHONES LEVEL: MAX							
0dBs=0,775V							
I TETE D'ENREGISTREMENT/LECTURE							
[1]	DEMAGNETISATION	—	—	POWER: OFF Eloigner la porte.	Tête D'ENREGISTREMENT/ LECTURE	Demagnétiser la tête D'ENREGISTREMENT/LECTURE avec un démagnétiseur de tête.	
[2]	NETTOYAGE	—	—	POWER: OFF Eloigner la porte.	Tête D'ENREGISTREMENT/ LECTURE tête d'effacement, cabestan, galetpresseur.	Nettoyer la tête D'ENREGISTREMENT/LECTURE la tête d'effacement, le cabestan et le galetpresseur avec un coton-tige légèrement imbibé d'alcool.	
[3]	AZIMUT	MTT-256 10kHz. -20dB	(B)	PLAY	Vis d'azimut	Ajuster la vis de réglage de l'azimut de façon que la tension de sortie soit maximale à la fois en avant et en arrière, de la bande d'essai.	(a)
II MOTEUR CC							
(i)	VITESSE DE DEFILEMENT	MTT-111 MTT-111D	(B)	PLAY	Résistance ajustable du moteur CC	Régler la vitesse de bande de façon qu'un signal de 3kHz soit produit au centre de la bande.	
III PLAQUE IMPRIMEE							
<1>	NIVEAU DE LECTURE	MTT-256 315Hz. 0dB	(B)	PLAY	VR3 (C) VR4 (D)	Niveau de sortie: -6.0dBs (390mV)	
<2>	COURANT DE POLARISATION	(A) 1kHz. -30dBs 10kHz. -30dBs	(B)	VR7 (C) VR8 (D)	Enregistrer un signal de 1kHz et 10kHz en alternance et ajuster les résistances variables qui commandent le courant de polarité de façon à obtenir le même niveau de lecture.		
<3>	NIVEAU D'ENREGISTREMENT	(A) 1kHz. -30dBs	(B)	VR5 (G) VR6 (D)	Enregistrer et reproduire un signal de 1kHz dans les conditions précisées en <2>.	Ajuster les résistances variables de façon à obtenir un niveau de lecture de -26dBs(39mV).	

VIS D'AZIMUT



RACCORDEMENTS DU SYSTEME

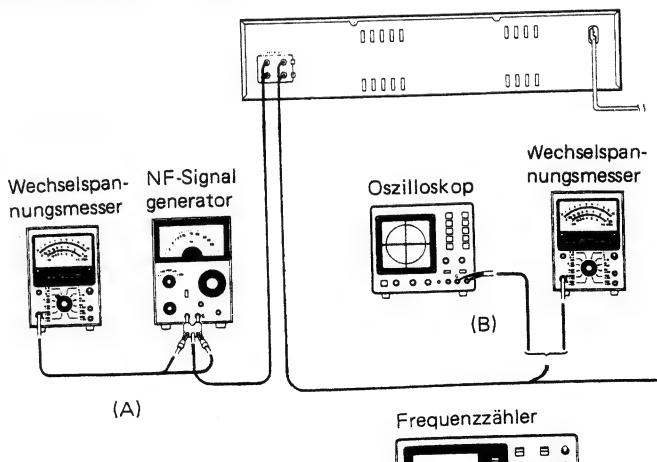
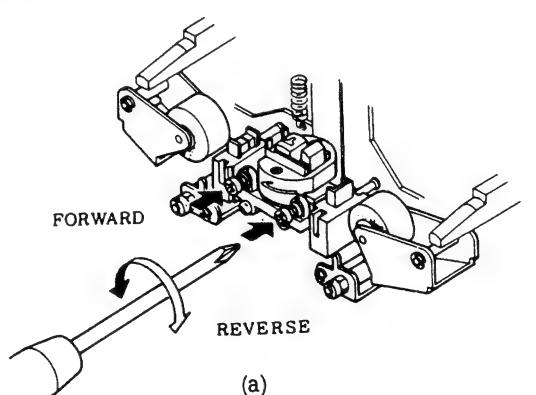


ABGLEICH

NR.	GEGENSTAND	EINGANGS-EINSTELLUNG	AUSGANGS-EINSTELLUNG	KASSETTENGERÄT-EINSTELLUNG	ABGLEICH-PUNKTE	ABGLEICHEN FÜR	ABB.
							0dBs=0,775V
I AUFGNAHME/WIEDERGABE-KOPF							
[1]	ENTMAGNETISIERUNG	—	—	POWER: OFF Den Kassettenfach deckel oben herausziehen.	AUFGNAHME/ WIEDERGABE-KOPF	Entmagnetisierung von dem AUFGNAHME/WIEDERGABE-Kopf mit einem Tonkopf Entmagnetisierungsdrössel.	
[2]	REINIGUNG	—	—	POWER: OFF Den Kassettenfach deckel oben herausziehen.	AUFGNAHME/ WIEDERGABE-Kopf Löschkopf, Tonwelle, Andrukrolle.	AUFGNAHME/WIEDERGABE-Kopf, Löschkopf, Tonwelle und Andrukrolle mit einem leicht mit Alkohol befeuchteten Wattebausch reinigen.	
[3]	AZIMUT-EINSTELLUNG	MTT-256 10kHz. -20dB	(B)	PLAY	Azimut-Einstellschraube	Die Azimut-Justierschraube so einstellen, daß die maximale Ausgangsspannung in Vorfächer-Reverserichtung und erzielt.	(a)
II GLEICHSTROMMOTOR							
(i)	BANDGESCHWINDIGKEIT	MTT-111 MTT-111D	(B)	PLAY	Trimmer potentiometer am Gleichstrommotor	Die Bandgeschwindigkeit so justieren, daß ein 3kHz Signal auf der Mitte des Bands erzeugt wird.	
III GEDRUCKTE SCHALTPLATTE							
<1>	WIEDERGABEPEGEL	MTT-256 315Hz. 0dB	(B)	PLAY	VR3 (L) VR4 (R)	Ausgangspegel: -6.0dBs (390mV)	
<2>	LEERLAUFSTROM	(A) 1kHz. -30dBs 10kHz. -30dBs	(B)	REC und BALANCE so justieren, daß der REC Monitorausgang -26dBs bei 1kHz wird, und danach abwechselnd Signale von 1kHz und 10kHz aufnehmen und wiedergeben.	VR7 (L) VR8 (R)	Signale von 1kHz und 10kHz abwechselnd aufnehmen und die Regelwiderstände, die den Vormagnetisierungsstrom regeln, so justieren, daß der gleiche Wiedergabepiegel erzielt wird.	
<3>	AUFGNAHMEPEGEL	(A) 1kHz. -30dBs	(B)	Ein 1kHz Signal unter den in Punkt <2> beschriebenen Bedingungen aufnehmen und reproduzieren.	VR5 (L) VR6 (R)	Die Regelwiderstände so justieren, daß ein wiedergabepiegel von -26dBs(39mV)erzielt wird.	

AZIMUTH-EINSTILLSCHRAUBE

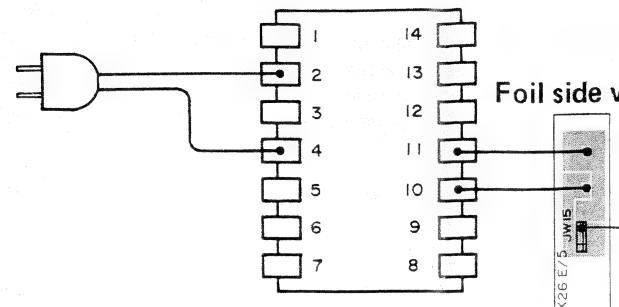
SYSTEM-ANSCHLUSSE



KX-790R KX-790R

PC BOARD

Refer to the schematic diagram for the values of resistors and capacitors.
The PC board drawing is viewing from the side easy to check.



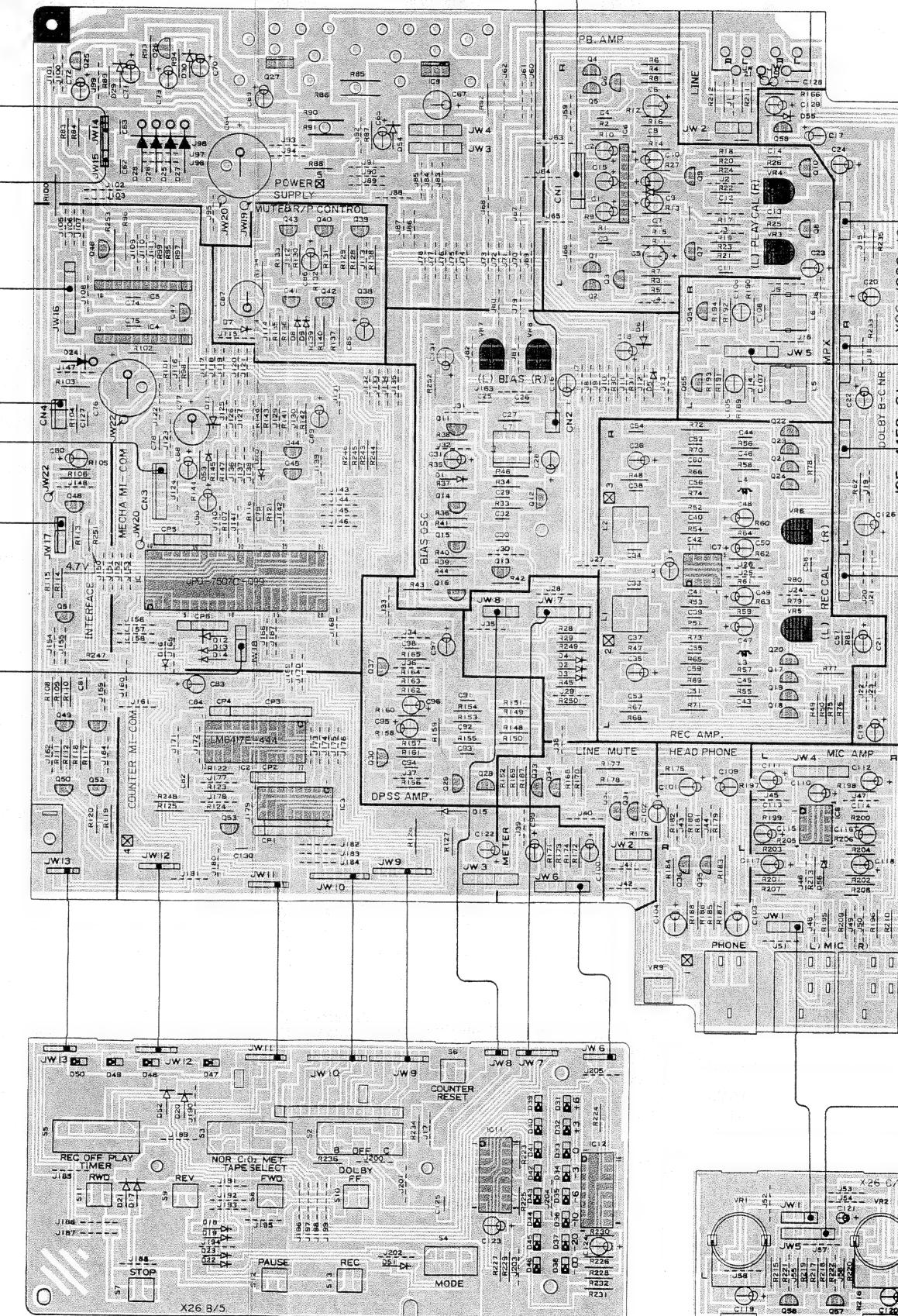
Foil side view

IC 1		
1	4.4V	21 2.1V
2	1.3V	22 —
3	1.3V	23 —
4	1.3V	24 —
5	1.3V	25 —
6	1.2V	26 —
7	1.2V	27 —
8	1.2V	28 4.8V(OV)
9	0V(1.2V)	29 4.8V(OV)
10	0V(4.8V)	30 0V(4V)
11	0V(4.8V)	31 4.7V
12	0V(4.8V)	32 3V(OV)
13	0V(4.8V)	33 0V
14	4.8V(OV)	34 4.9V
15	0V(4.8V)	35 4.9V
16	4.8V	36 0V
17	4.8V	37 0V
18	0V	38 0V
19	2.2V	39 0V
20	4.9V	40 0V

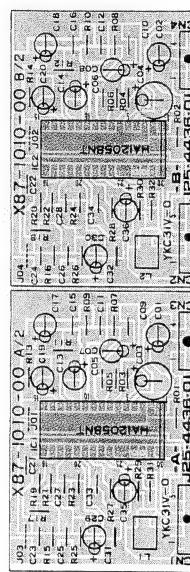
MECHA. ASS'Y (D40-0317-05)

IC4		IC5		IC11,12	
7	13.6V	7	14.3V	1	9.8
8		8	9.8V	2	11.5V
IC6		IC 7,8		3	1.3V
1	1.3V	1	7.5V	4	11.5V
2	0.77V	2	7.5V	5	13V
3	3.4V	3	7.5V	6	11.5V
4	12.0V	4	0V	7	13V
5	0V	5	7.5V	8	0V
6	3.4V	6	7.5V	9	0.6V
7	0.77V	7	7.5V	10	15V
8	1.3V	8	15V	11	0V
IC9				12	0V
IN	—			13	0V
OUT	15.0V			14	2.6V
GND	0V			15	0V
				16	0.7V
JW4		JW5		JW6	

CASSETTE UNIT (X26-1090-10) Component side view

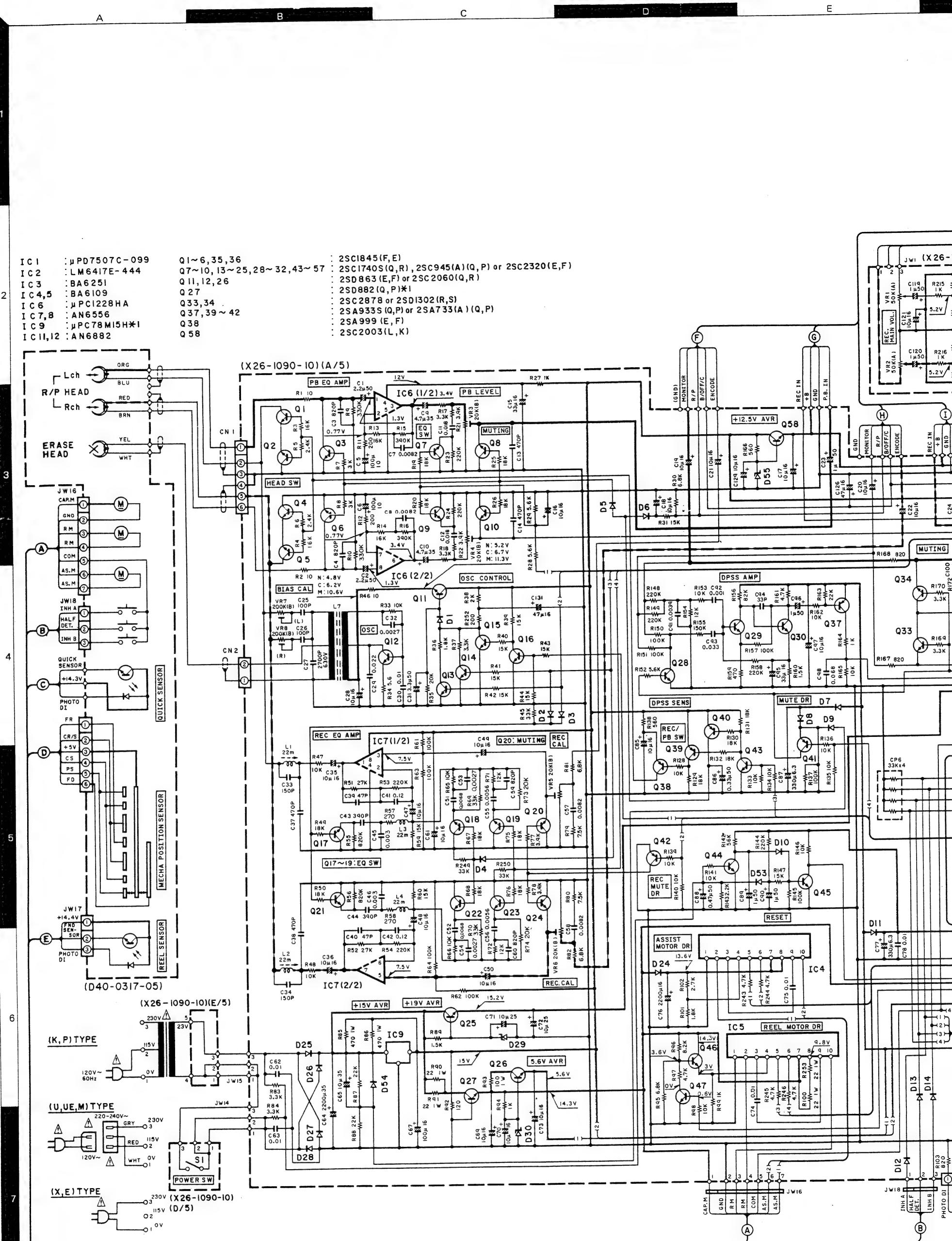


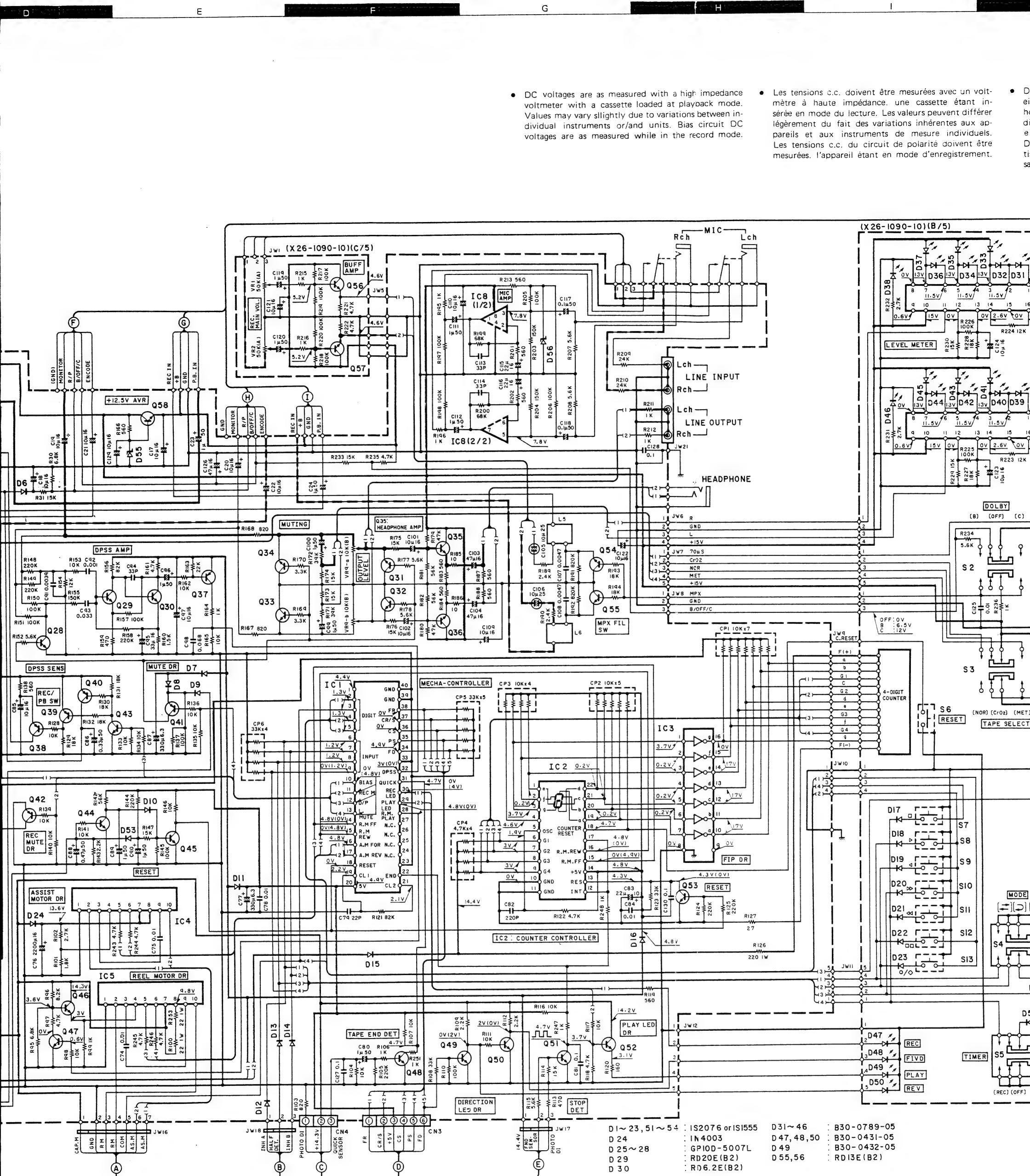
DOLBY UNIT (X87-1010-00)
Component side view



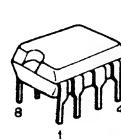
IC 1,2		
1	12.2V	16 60V
2	6.0V	17 6.1V
3	6.1V	18 6.1V
4	0V	19 6.1V
5	3.7V	20 6.1V
6	6.1V	21 1V(2V)
7	6.2V	22 0.7V
8	6.2V	23 6.3V
9	6.1V	24 6.4V
10	6.1V	25 6.4V
11	0V	26 6.4V
12	0.9V	27 —
13	0.6V	28 —
14	0V	29 0V(4.3V)
15	5.4V	30 OFF 4.5V
		B 6.1V
		C 8.1V

FRONT

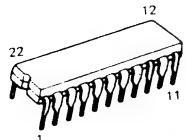




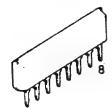
AN6556



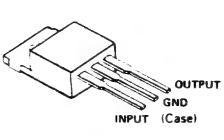
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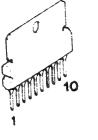
μPC1228HA



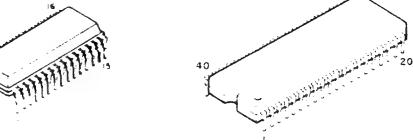
μPC78M15H*1



BA6109



HA12058NT



D1~23, 31~54 : IS2076 or IS1555
 D24 : IN4003
 D25~28 : GPIOD-5007L
 D29 : RD20E(B2)
 D30 : RD6.2E(B2)

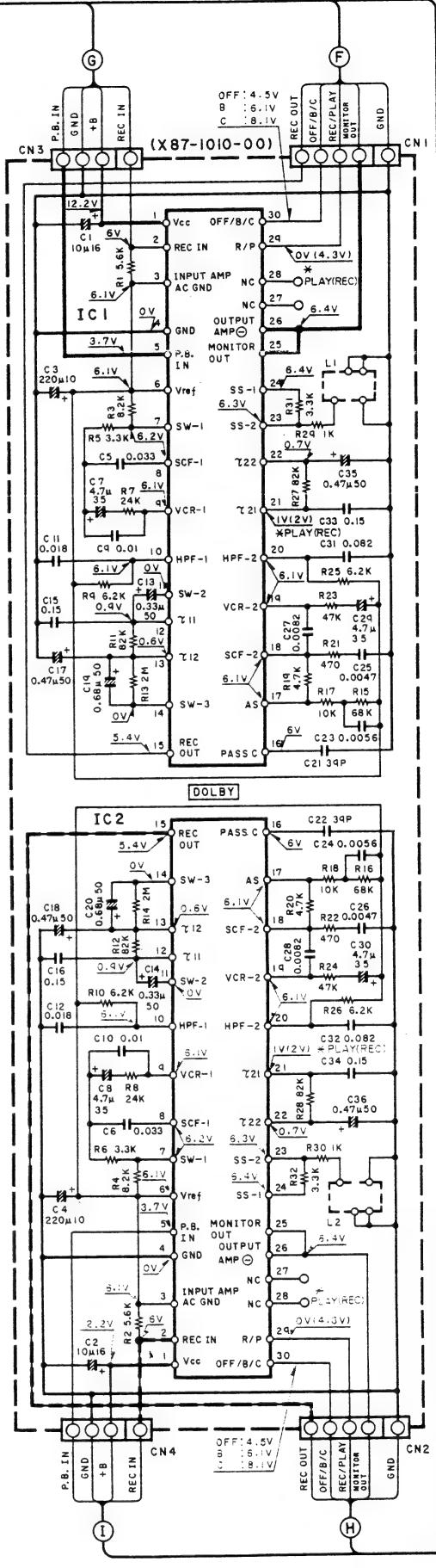
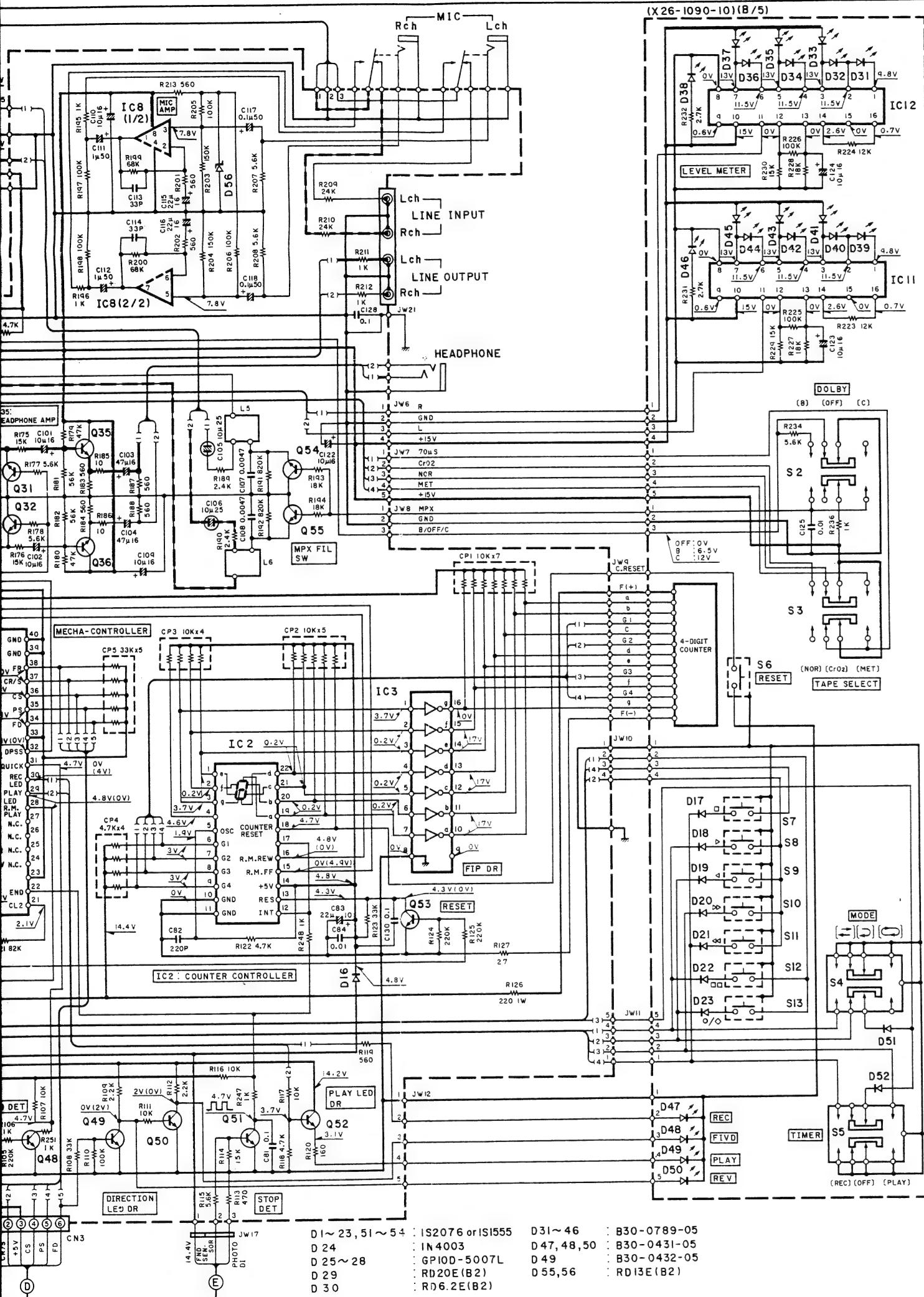
D31~46 : B30-0789-05
 D47, 48, 50 : B30-0431-05
 D49 : B30-0432-05
 D55, 56 : RD13E(B2)

△ Indicates safety

- DC voltages are as measured with a high impedance voltmeter with a cassette loaded at playback mode. Values may vary slightly due to variations between individual instruments or/and units. Bias circuit DC voltages are as measured while in the record mode.

- Les tensions c.c. doivent être mesurées avec un voltmètre à haute impédance, une cassette étant insérée en mode du lecture. Les valeurs peuvent différer légèrement du fait des variations inhérentes aux appareils et aux instruments de mesure individuels. Les tensions c.c. du circuit de polarité doivent être mesurées, l'appareil étant en mode d'enregistrement.

- Die angegeben Gleichspannungswerte wurden bei eingesetzter Cassette in der Wiedergabe mit einem hochohmigen Voltmeter gemessen. Dabei schwanken die Meßwerte aufgrund von Unterschieden zwischen einzelnen Instrumenten oder Geräten u.U. geringfügig. Die angegeben Gleichspannungswerte der Vormagnetisierungsschaltung wurden in der Aufnahme-Betriebsart gemessen.



IC1,2 : HA12058NT

KX-790R/K

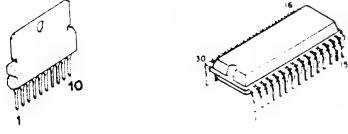
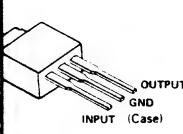
154 *

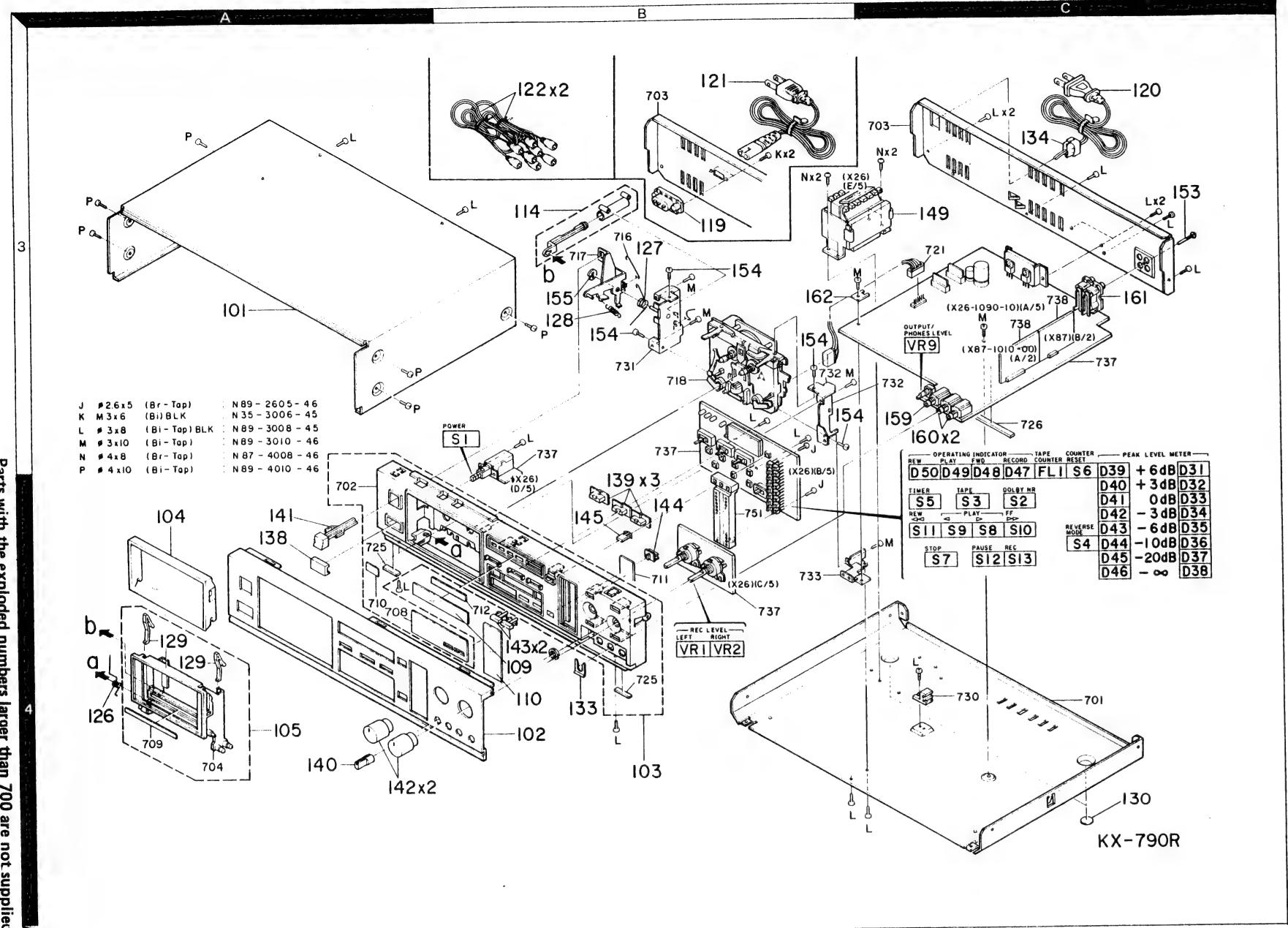
BA6109

HA12058NT

μPD7507C-099

▲Indicates safety critical component.





STER

KENWOOD

KX-790R **KX-790R**

PARTS LIST

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Teile ohne **Parts No.** werden nicht geliefert.

Ref. No. 參照番号	Address 位 置	New Parts 新	Parts No. 部品番号	Description 部品名 / 規格	Desti- nation 仕 向	Re- marks 備考
KX-790R						
101	3A	*	A01-1348-02	METALLIC CABINET		
102	4B	*	A20-4093-02	PANEL		
103	4B	*	A22-0462-03	SUB PANEL ASSY		
104	4A	*	A53-0626-03	CASSETTE LID		
105	4A	*	A53-0627-03	CASSETTE HOLDER ASSY		
109	4B	*	B08-0036-04	INDICATOR(OP IND,TAPE COUNTER)		
110	4B	*	B08-0037-04	INDICATOR(PEAK LEVEL METER)	K	
-			B46-0092-03	WARRANTY CARD	P	
-			B46-0093-03	WARRANTY CARD	UUE	
-			B46-0094-03	WARRANTY CARD		
-			B46-0095-03	WARRANTY CARD	UUE	
-			B46-0096-03	WARRANTY CARD	X	
-			B46-0098-03	WARRANTY CARD	E	
-		*	B50-5369-00	INSTRUCTION MANUAL(ENGLISH)		
-		*	B50-5370-00	INSTRUCTION MANUAL(FRENCH)	PMXE	
-		*	B50-5371-00	INSTRUCTION MANUAL(SPANISH)	M	
-		*	B50-5422-00	INSTRUCTION MANUAL(G,D,I)	E	
-		*	B50-5427-00	INSTRUCTION MANUAL(ARABIC)	M	
-			B58-0223-04	CAUTION CARD	U	
-			B58-0269-04	CAUTION CARD	K	
-			B58-0513-04	CAUTION CARD	UE	
-			B59-0092-00	SERVICE DIRECTORY	UUE	
114	3B	*	D39-0172-05	DAMPER ASSY		
△ 119	3B		E03-0102-15	AC INLET	UMUE	
△ 120	3C		E30-0181-05	AC POWER CORD	KP	
△ 120	3C		E30-0459-05	AC POWER CORD	E	
△ 120	3C		E30-1341-05	AC POWER CORD	X	
△ 121	3B		E30-1305-15	AC POWER CORD (INLET)	UMUE	
122	3B		E30-0505-05	AUDIO CORD		
126	4A	*	G01-1527-04	TORSION COIL SPRING (C HOLDER)		
127	3B	*	G01-1528-04	TORSION COIL SPRING (LOCK PLT)		
128	3B	*	G01-1557-04	EXTENSION SPRING (LOCK PLT)		
129	4A		G02-0123-04	FLAT SPRING (CASSETTE HOLDER)		
130	4C	*	G11-1103-04	CUSHION (UNDER CHASSIS)		
-		*	H01-5242-04	ITEM CARTON CASE		
-		*	H10-1763-04	POLYSTYRENE FOAMED FIXTURE		
-		*	H10-1764-04	POLYSTYRENE FORMED FIXTURE		
-		*	H12-0185-04	PACKING FIXTURE	M	
-			H20-0417-04	PROTECTION COVER		
-			H25-0078-04	PROTECTION BAG		
-			H25-0224-04	PROTECTION BAG	KPUUE	
-			H25-0224-04	PROTECTION BAG	XE	
-			H40-0005-04	RUST PREVENTING PAPER	M	
△ 133	4B		J21-3326-05	JACK MOUNTING HARDWARE		
134	3C		J42-0083-05	POWER CORD BUSHING		
-			J61-0307-05	WIRE BAND	KPXE	
138	4A	*	K27-1325-04	KNOB (BUTTON) POWER		
139	4B	*	K27-1326-04	KNOB (LEVER) TIMER,TAPE,DOLBY		
140	4A		K29-1327-04	KNOB OUTPUT/PHONE LEVEL		
141	4A	*	K29-1853-04	KNOB (BTN) EJECT		
142	4A	*	K29-1854-04	KNOB REC LEVEL		

C: South Africa T: England U: PY(Ear, East, Hawaii)

B: Canada

 indicates safety critical components.

Exploded numbers larger than 700 are not supplied.

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143	4B	*	K29-1855-04	KNOB (BTN)	PAUSE, REC			
144	4B	*	K29-1856-04	KNOB (LVR)	REVERSE MODE			
145	4B	*	K29-1940-04	KNOB (BTN)	COUNTER RESET			
149	3C	*	L01-3844-05	POWER TRANSFORMER				
153	3C		ND9-0301-05	STEPPED SCREW (GND)				
154	3B, 3C		ND9-1337-05	TAPITTE SCREW (MOUNT HARDWARE)				
155	3B		N29-0207-04	RETAINING RING (LOCK PLATE)				
CASSETTE (X26-1090-10)								
D31 -46	4C		B30-0789-05	LED(LN245RP)	LEVEL METER			
D47 ,48	4C		B30-0431-05	LED(LN21CPH)	RECORD, FWD			
D49	4C		B30-0432-05	LED(LN31GCPH(U))	PLAY			
D50	4C		B30-0431-05	LED(LN21CPH)	REV			
C1 ,2			CEO4FW1H2R2MEL	ELECTRO	2.2UF	50WV		
C3 ,4			CQ09FS1H821JZS	POLYSTY	820PF	J		
C5 ,6			CEO4FW1A101MEL	ELECTRO	100UF	10WV		
C7 ,8			CF92FV1H822J	MF	8200PF	J		
C9 ,10			CEO4FW1V4R7MEL	ELECTRO	4.7UF	35WV		
C11 ,12			CF92FV1H183J	MF	0.018UF	J		
C13 ,14			CK45FB1H471K	CERAMIC	470PF	K		
C15			CEO4FW1C330MEL	ELECTRO	33UF	16WV		
C16 -22			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C23 ,24			CEO4FW1H010MEL	ELECTRO	1.0UF	50WV		
C25 ,26			CC45FSL1H101J	CERAMIC	100PF	J		
C27			C91-0348-05	POLYPR	0.0027UF	630WV		
C28			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C29			CF92FV1H223J	MF	0.022UF	J		
C30			CF92FV1H103J	MF	0.010UF	J		
C31			CEO4FW1H3R3MEL	ELECTRO	3.3UF	50WV		
C32			CF92FV1H272J	MF	2700PF	J		
C33 ,34			CC45FSL1H151J	CERAMIC	150PF	J		
C35 ,36			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C37 ,38			CK45FB1H471K	CERAMIC	470PF	K		
C39 ,40			CC45FSL1H470J	CERAMIC	47PF	J		
C41 ,42			CF92FV1H124J	MF	0.12UF	J		
C43 ,44			CQ09FS1H391JZS	POLYSTY	390PF	J		
C45 ,46			CF92FV1H302J	MF	3000PF	J		
C47 -50			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C51 ,52			CF92FV1H682J	MF	6800PF	J		
C53 ,54			CF92FV1H272J	MF	2700PF	J		
C55 ,56			CF92FV1H562J	MF	5600PF	J		
C57 ,58			CF92FV1H822J	MF	8200PF	J		
C59 ,60			CQ09FS1H821JZS	POLYSTY	820PF	J		
C61			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C62 ,63			CK45FF1H103Z	CERAMIC	0.01UF	Z		
C64			CEO4W1V222MEL	ELECTRO	2200UF	35WV		
C65			CEO4FW1V100MEL	ELECTRO	10UF	35WV		
C67			CEO4FW1C101MEL	ELECTRO	100UF	16WV		
C69 ,70			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C71 ,72			CEO4FW1E100MEL	ELECTRO	10UF	25WV		
C73			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C74 ,75			CK45FF1H103Z	CERAMIC	0.01UF	Z		
C76			CEO4W1C222MEL	ELECTRO	2200UF	16WV		
C77		*	CEO4FW0J331MEL	ELECTRO	330UF	6.3WV		

E: Scandinavia & Europe H: Audio Club K: USA

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C78			CK45FF1H103Z	CERAMIC	0.01UF	Z					
C79			CK45FSL1H220J	CERAMIC	22PF	J					
C80			CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C81			C91-0700-05	CERAMIC	0.1UF	J					
C82			CC45FSL1H221J	CERAMIC	220PF	J					
C83			CEO4FW1A220MEL	ELECTRO	22UF	10WV					
C84			CK45FF1H103Z	CERAMIC	0.01UF	Z					
C85			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C86			CEO4FW1HR33MEL	ELECTRO	0.33UF	50WV					
C87		*	CEO4FW0J331MEL	ELECTRO	330UF	6.3WV					
C88			CEO4FW1HR47MEL	ELECTRO	0.47UF	50WV					
C89	, 90		CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C91			CF92FV1H392J	MF	3900PF	J					
C92			CF92FV1H102J	MF	1000PF	J					
C93			CF92FV1H333J	MF	0.033UF	J					
C94			CC45FSL1H330J	CERAMIC	33PF	J					
C95			CEO4FW1C330MEL	ELECTRO	33UF	16WV					
C96			CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C97			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C98			CF92FV1H683J	MF	0.068UF	J					
C99	, 100		CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C101, 102			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C103, 104			CEO4FW1C470MEL	ELECTRO	47UF	16WV					
C105, 106			CEO4HW1E100M	NP-ELEC	10UF	25WV					
C107, 108			CF92FV1H472J	MF	4700PF	J					
C109, 110			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C111, 112			CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C113, 114			CC45FSL1H330J	CERAMIC	33PF	J					
C115, 116			CEO4FW1C220MEL	ELECTRO	22UF	16WV					
C117, 118			CEO4FW1H0R1MEL	ELECTRO	0.1UF	50WV					
C119, 120			CEO4FW1H010MEL	ELECTRO	1.0UF	50WV					
C121		*	CEO4JW1C100MEL	ELECTRO	10UF	16WV					
C122-124			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C125			CK45FF1H103Z	CERAMIC	0.01UF	Z					
C126			CEO4FW1C470MEL	ELECTRO	47UF	16WV					
C127, 128			C91-0700-05	CERAMIC	0.1UF	J					
C129			CEO4FW1C100MEL	ELECTRO	10UF	16WV					
C130			C91-0700-05	CERAMIC	0.1UF	J					
C131			CEO4FW1C470MEL	ELECTRO	47UF	16WV					
159	3C	*	E11-0104-15	PHONE JACK	(HEADPHONE)						
160	3C	*	E11-0151-05	PHONE JACK	(MIC)						
161	3C		E13-0445-05	PHONE JACK	(LINE IN/OUT)						
162	3B		E23-0125-05	TERMINAL	(GND PLATE)						
L1 , 2		*	L39-0312-05	VARIABLE INDUCTOR(BIAS TRAP)							
L3 , 4		*	L40-2238-29	SMALL FIXED INDUCTOR (0.022H)							
L5 , 6			L79-0196-05	LC FILTER (BSF) 85KHZ							
L7			L32-0285-05	BIAS OSCILATING COIL							
CP1			R90-0234-05	MULTI-COMP	10KX7	J					
CP2			R90-0228-05	MULTI-COMP	10KX5	J					
CP3			R90-0233-05	MULTI-COMP	10KX4	J					
CP4		*	R90-0286-05	MULTI-COMP	4.7KX4	J					
CP5			R90-0236-05	MULTI-COMP	33KX5	J					
CP6			R90-0277-05	MULTI-COMP	33KX4	J					
R46			R92-0219-05	FUSE RESIST	10		1/4W				

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R85 ,86 R90 ,91 R92 R93 R100		*	RS14KB3A471J RS14KB3A220J RD14GB2E121J RS14KB3A101J RS14KB3A220J	FL-PROOF RS 470 FL-PROOF RS 22 FL-PROOF RD 120 FL-PROOF RS 100 FL-PROOF RS 22	J 1W J 1W J 1/4W J 1W J 1W				
R126 R253 VR1 ,2 VR3 -6 VR7 ,8	4B	*	RS14KB3A221J RS14KB3A220J R01-4031-05 R12-3313-05 R12-5310-05	FL-PROOF RS 220 FL-PROOF RS 22 POTENTIOMETER(REC LEVEL) TRIMMING POT. (20K)PB REC LEVEL TRIMMING POT. (200K)BIAS	J 1W J 1W				
VR9	3C	*	R10-3023-05	POTENTIOMETER(OUTPUT/PHONE LVL)					
S1 ,3 S2 S4 S5 S6 -13		*	S40-1089-05 S31-2091-05 S31-2062-05 S31-2091-05 S40-1085-05	PUSH SWITCH (POWER) SLIDE SWITCH(DOLBY NR,TAPE) SLIDE SWITCH(VERSE MODE) SLIDE SWITCH(TIMER) PUSH SWITCH (C RESET,OP KEY)					
D1 -23 D1 -23 D24 D25 -28 D29			1S1555 1S2076 1N4003 GP10D-5007L RD20E (B2)	DIODE DIODE DIODE DIODE ZENER DIODE					
D30 D51 -54 D51 -54 D55 ,56 D57			RD6.2E(B2) 1S1555 1S2076 RD13E(B2) RD5.1E(B2)	ZENER DIODE DIODE DIODE ZENER DIODE ZENER DIODE					
FL1 IC1 IC2 IC3 IC3		*	4-ST-41ZYK UPD7507C-099 LM6417E-444 BA6251 TD62501P	FLUORESCENT INDICATOR TUBE IC(MICROPROCESSOR) IC(MICROPROCESSOR) IC(7-CH TRANSISTOR ARRAY) IC(7-CH TRANSISTOR ARRAY)					
IC4 ,5 IC6 IC7 ,8 IC9 IC11,12		*	BA6109 UPC1228HA AN6556 UPC78M15H*1 AN6882	IC(MOTOR DRIVER) IC(TAPE EQ AMP) IC(OP AMP) IC(VOLTAGE REGULATOR) +15V IC(METER DRIVER)					
Q1 -6 Q7 -10 Q7 -10 Q7 -10 Q11 ,12			2SC1B45(F,E) 2SC1740S(Q,R) 2SC2320(E,F) 2SC945(A)(Q,P) 2SC2060(Q,R)	TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR					
Q11 ,12 Q13 -25 Q13 -25 Q13 -25 Q26			2SD863 2SC1740S(Q,R) 2SC2320(E,F) 2SC945(A)(Q,P) 2SC2060(Q,R)	TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR					
Q26 Q27 Q28 -32 Q28 -32 Q28 -32			2SD863 2SD882*1(Q,P) 2SC1740S(Q,R) 2SC2320(E,F) 2SC945(A)(Q,P)	TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR					
Q33 ,34 Q35 ,36 Q37			2SD1302(S) 2SC1B45(F,E) 2SA733(A)(Q,P)	TRANSISTOR TRANSISTOR TRANSISTOR					

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Q37			2SA933S(Q,R)	TRANSISTOR		
Q37			2SA999(E,F)	TRANSISTOR		
Q38			2SA992(F,E)	TRANSISTOR		
Q39 -42			2SA733(A)(Q,P)	TRANSISTOR		
Q39 -42			2SA933S(Q,R)	TRANSISTOR		
Q39 -42			2SA999(E,F)	TRANSISTOR		
Q43 -57			2SC1740S(Q,R)	TRANSISTOR		
Q43 -57			2SC2320(E,F)	TRANSISTOR		
Q43 -57			2SC945(A)(Q,P)	TRANSISTOR		
Q58			2SC2003(L,K)	TRANSISTOR		

DOLBY NR (X87-1010-00)

C1 ,2			CEO4FW1C100MEL	ELECTRO	10UF	16WV		
C3 ,4			CEO4FW1A221MEL	ELECTRO	220UF	10WV		
C5 ,6			CF92FV1H333J	MF	0.033UF	J		
C7 ,8			CEO4FW1V4R7MEL	ELECTRO	4.7UF	35WV		
C9 ,10			CF92FV1H103J	MF	0.010UF	J		
C11 ,12			CF92FV1H183J	MF	0.018UF	J		
C13 ,14			CEO4FW1HR33MEL	ELECTRO	0.33UF	50WV		
C15 ,16			CF92FV1H154J	MF	0.15UF	J		
C17 ,18			CEO4FW1HR47MEL	ELECTRO	0.47UF	50WV		
C19 ,20		*	CEO4GW1HR68MEL	LL-ELEC	0.68UF	50WV		
C21 ,22			CC45FSL1H390J	CERAMIC	39PF	J		
C23 ,24			CF92FV1H562J	MF	5600PF	J		
C25 ,26			CF92FV1H472J	MF	4700PF	J		
C27 ,28			CF92FV1H822J	MF	8200PF	J		
C29 ,30			CEO4FW1V4R7MEL	ELECTRO	4.7UF	35WV		
C31 ,32		*	CF92FV1H823J	MF	0.082UF	J		
C33 ,34		*	CF92FV1H154J	MF	0.15UF	J		
C35 ,36		*	CEO4FW1HR47MEL	ELECTRO	0.47UF	50WV		
L1 ,2			L39-0106-05	TRAP COIL	(20KHZ)			
IC1 ,2		*	HA12058NT	IC(DOLBY)				

CASSETTE MECHANISM (D40-0317-05)

1	2C		A10-0774-08	CHASSIS ASSY			
5	1B		B19-0349-08	MIRROR			
9	2B		D01-0063-08	FLYWHEEL ASSY			
10	1B		D03-0231-08	REEL DISK ASSY (R)			
11	1B		D03-0232-08	REEL DISK ASSY (L)			
12	1B		D10-1352-08	LEVER ASSY (REC DETECT)			
13	1B		D10-1353-08	LEVER ASSY (CASSETTE-IN DET)			
14	2C		D10-1354-08	LEVER ASSY (BRAKE L)			
15	1C		D10-1355-08	LEVER ASSY (BRAKE R)			
16	1B		D10-1356-08	ARM (EJECT PREVENT L)			
17	1C		D10-1357-08	ARM (DETECTION)			
18	1A		D10-1358-08	SLIDER (PLATE HEAD)			
19	1A		D10-1359-08	SLIDER (C/R SLIDE PLATE)			
20	1A		D10-1360-08	SLIDER (SLIDE BASE L)			
21	1B		D10-1361-08	SLIDER (SLIDE BASE R)			
22	2C		D10-1362-08	SLIDER (SWITCHOVER)			
23	1B		D13-0197-08	GEAR ASSY (IDLER ASSY)			
24	2C		D13-0198-08	GEAR ASSY			
25	1C		D13-0199-08	GEAR (WORM)			
26	2C		D13-0200-08	GEAR (IDLE)			

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27	2A		D14-0117-08	PINCH ROLLER ASSY (L)		
28	2A		D14-0118-08	PINCH ROLLER ASSY (R)		
29	2B		D16-0110-08	BELT (MAIN)		
30	2B		D23-0197-08	RETAINER (FLYWHEEL)		
31	2A, 2B		D40-0327-08	MECHANISM ASSY (COMBI HEAD)		
32	2A		D90-0025-08	STEEL BALL		
-			E31-3513-08	CONNECTING WIRE (REC/PLAY)		
-			E31-3514-08	CONNECTING WIRE (ERASE)		
-			E31-3515-08	CONNECTING WIRE (TAPE SENSOR)		
36	2B		F10-0551-08	SHIELDING PLATE (PCB)		
40	2C		G01-1579-08	TENSION SPRING (BRAKE)		
41	2A		G01-1580-08	TENSION SPRING (CR SLIDE)		
42	2A		G01-1581-08	TORSION SPRING (ADJ L)		
43	2A		G01-1582-08	TORSION SPRING (ADJ R)		
44	2A		G01-1583-08	TORSION SPRING (PNCH ROLLER L)		
45	2A		G01-1584-08	TORSION SPRING (PNCH ROLLER R)		
46	1A		G01-1585-08	TORSION SPRING (SLIDE BASE L)		
47	2B		G01-1586-08	TORSION SPRING (SLIDE BASE R)		
48	1B		G01-1587-08	TORSION SPRING (HEAD BASE)		
49	1A		G02-0177-08	FLAT SPRING (CR SLIDE PLATE)		
50	1C		G02-0178-08	FLAT SPRING (THRUST)		
51	1B		G02-0179-08	FLAT SPRING (CASSETTE PACK L)		
52	1C		G02-0180-08	FLAT SPRING (CASSETTE PACK R)		
53	2C		G02-0181-08	SPIRAL SPRING		
57	2B		J19-0306-05	HOLDER (WIRE)		
58	1B		J19-2188-08	HOLDER (HEAD LEAD)		
59	1C		J21-3562-08	MOUNTING HARDWARE (ASSIST MTR)		
60	2B		J21-3563-08	MOUNTING HARDWARE (MAIN MTR)		
61	2C		J25-4501-08	PRINTED WIRING BOARD (DETECT)		
62	1C		J25-4502-08	PRINTED WIRING BOARD (CONNECT)		
63	1B, 1C		J39-0084-08	SPACER (COLLAR)		
64	2A		J90-0151-08	TAPE GUIDE (WITH SENSOR)		
65	2A		J90-0152-08	TAPE GUIDE		
69	2A		N09-1433-08	SCREW (M2X5)		
70	1C		N09-1434-08	SCREW (M2X3.5)		
71	2B		N09-1435-08	SCREW (M2.6X3.5)		
72	2A		N14-0150-08	NUT		
73	2C		N15-1026-46	FLAT WASHER		
74	2B		N17-1030-46	TOTCHED LOCK WASHER		
75	1B		N19-0369-04	FLAT WASHER (#2.5)		
76	1B		N19-0524-04	FLAT WASHER (#2X3.8X0.25)		
77	1B, 1C		N19-0903-08	FLAT WASHER (#1.6X3.8X0.25)		
78	1B		N19-0904-08	FLAT WASHER (#2.1X#7X0.13)		
79	2B, 2C		N19-0905-08	FLAT WASHER (#2.6X0.25)		
80	2A		N24-3025-45	E TYPE RETAINING RING		
89	2C		T42-0058-08	DC MOTOR ASSY (REEL)		
90	1C		T42-0059-08	DC MOTOR ASSY (ASSIST)		
91	2B		T42-0060-08	DC MOTOR ASSY (MAIN)		
-			T34-0311-08	REC/PLAY HEAD		

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Note :

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TRIO-KENWOOD CORPORATION

Shionogi Shibuya Building, 17-5, 2-chome Shibuya, Shibuya-ku, Tokyo 151, Japan

KENWOOD ELECTRONICS

1315 E. Watsoncenter Rd., Carson, California 90745, U.S.A.
75 Seaview Drive, Secaucus, New Jersey 07094, U.S.A.

TRIO-KENWOOD CANADA INC.

1070 Jayson Court, Mississauga, Ontario, Canada L4W 2V5

TRIO-KENWOOD ELECTRONICS, N.V.

Leuvensesteenweg 504 B-1930 Zaventem, Belgium

TRIO-KENWOOD ELECTRONICS GmbH

Rudolf-Brass-Str. 20, 6056 Heusenstamm, West Germany

TRIO-KENWOOD FRANCE S.A.

5, Boulevard Ney, 75018 Paris, France

TRIO-KENWOOD (AUSTRALIA) PTY LTD (INCORPORATED IN N.S.W.)

4E Woodcock Place, Lane Cove, N.S.W. 2066, Australia

KENWOOD & LEE ELECTRONICS, LTD

Wang Kee Building, 5th Floor, 34-37, Connaught Road, Central, Hong Kong

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